

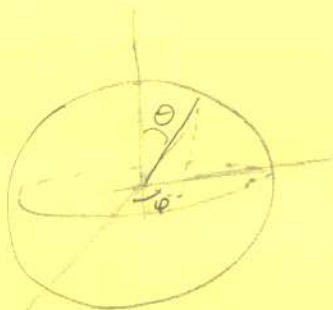
①

MANIFOLDS

TODAY WE'LL DISCUSS MANIFOLDS, & SOME STRUCTURES ON THEM.
I'LL TELL YOU WHAT PHYSICISTS ACTUALLY MEAN WHEN WE
WRITE THINGS LIKE

$$\phi(x^{\mu})$$

FOR FUNCTIONS OR VECTORS ON SOME MANIFOLD. ^{→ NEXT WEEK!} FIRST, LET'S
GIVE A SIMPLE MOTIVATION, S^2 . WE ALL KNOW THAT
GIVEN ANY POINT ON S^2 , ANGLES θ & φ MAY BE GIVEN
TO DESCRIBE THE POINT.



THE PROBLEM IS, THE SPECIFICATION IS
NOT UNIQUE, $(\theta, \varphi) = (0, a), (0, b)$
& $(\theta, \varphi) = (3, 0), (3, 2\pi)$

DEFINE THE SAME POINTS WITH DIFFERENT
NUMBERS. WE CANNOT DESCRIBE COORDINATES

IN THE USUAL WAY, OR DO DIFFERENTIATION AS EXPECTED; WHAT
HAPPENS TO $\partial_{\varphi} f$ AS $\theta \rightarrow 0$? TO BE WELL DEFINED, IT MUST
GO TO ZERO, BUT A COORDINATE SHOULDN'T DEPEND ON OTHER
COORDINATES.

THE DEFINITION OF A MANIFOLD AVOIDS THESE PROBLEMS BY
INTRODUCING "LOCAL COORDINATES"

(2)

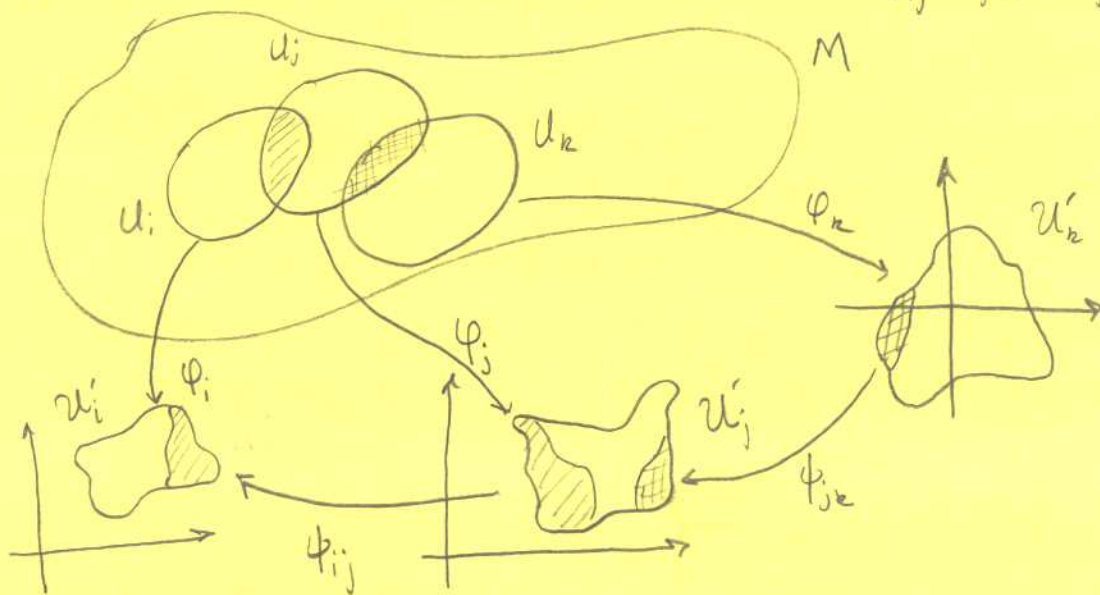
A MANIFOLD M IS

- (1) A TOPOLOGICAL SPACE (M, \mathcal{T})
(2) A FAMILY OF OPEN SETS $\{U_i\} \subseteq \mathcal{T}$, WITH $\bigcup_i U_i = M$
& HOMEOMORPHISMS $\{\varphi_i\}$ (CTS FCTS w/ CTS INVERSES)

$$\varphi_i: U_i \rightarrow \mathcal{U}'_i \subset \mathbb{R}^n$$

TO OPEN SETS \mathcal{U}'_i IN \mathbb{R}^n . BASICALLY THIS SAYS THAT φ_i "ELASTICALLY" DEFORMS U_i INTO \mathcal{U}'_i .

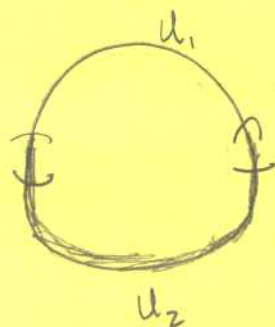
- (3) FOR EACH $U_{ij} = U_i \cap U_j$, $U_{ij} \neq \emptyset$, THERE EXISTS A SMOOTH (∞^{th} DIFFERENTIABLY) MAP $\varphi_{ij}: U_{ij} \rightarrow \mathcal{U}'_{ij}$
 $\varphi_{ij}: \varphi_j(U_i \cap U_j) \rightarrow \varphi_i(U_i \cap U_j)$



NOTE; BECAUSE φ_i & φ_i^{-1} ARE CTS, $\varphi_i(U_i \cap U_j) \subseteq \mathcal{U}'_i$ IS OPEN! FURTHERMORE φ_{ij} IS ONLY DEFINED FOR THE MARKED AREA INSIDE \mathcal{U}'_j ... IT NEED NOT MAKE SENSE ELSEWHERE!

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Let's do the simplest non-trivial example, S^1 .



$$U_1 = (\pi - \epsilon, \pi + \epsilon)$$

$$U_2 = (\pi - \epsilon, 2\pi + \epsilon)$$

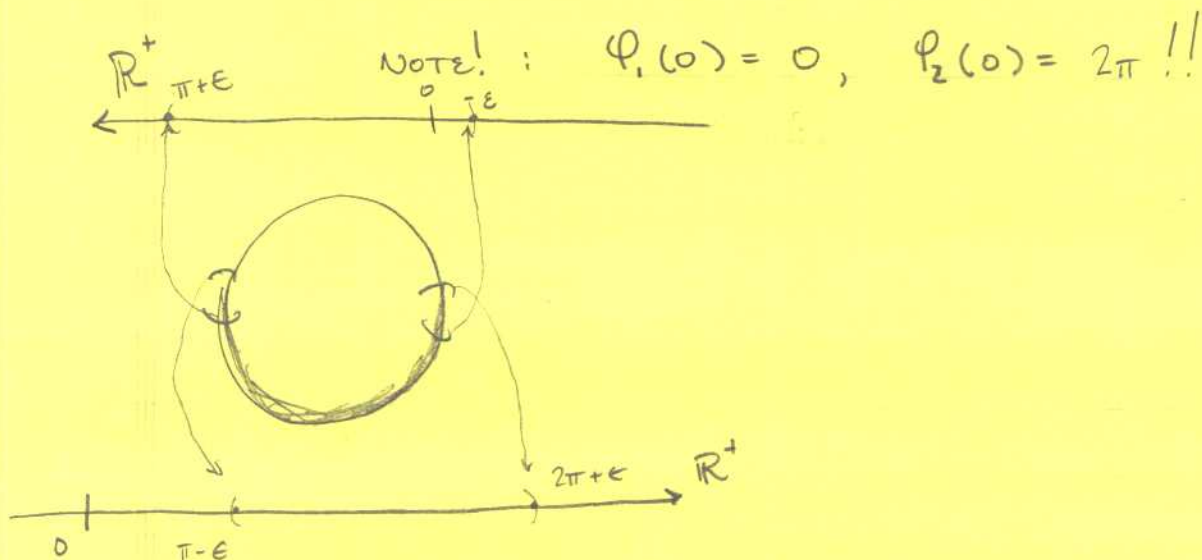
$$\text{and } U_1 \cap U_2 = (-\epsilon, \epsilon) \cup (\pi - \epsilon, \pi + \epsilon)$$

One can check that $(S^1, \{U_1, U_2, U_1 \cap U_2\})$ is a topological space. Now, we choose our open sets to be $\{U_1, U_2\}$, and we must define homeomorphisms

$$\varphi_1: U_1 \rightarrow \mathbb{R}$$

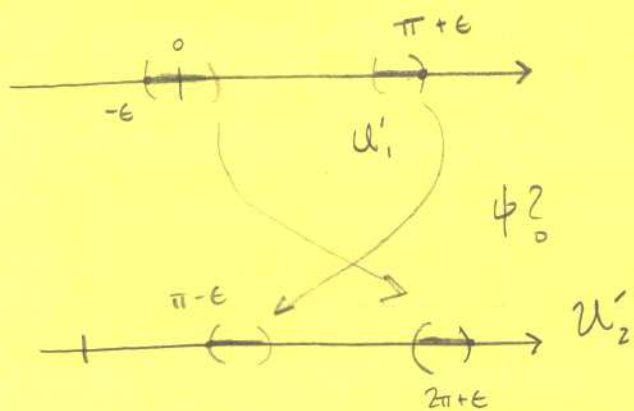
$$\varphi_2: U_2 \rightarrow \mathbb{R}$$

This is easy, set $\varphi_1(0) = 0$ and $\varphi_2(0) = 0$



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So, WE HAVE



ξ ψ_{21} HAS TO REVERSE THE ORDER!

$$\psi_{21}(\pi+\epsilon) = \pi+\epsilon$$

$$\psi_{21}(\pi-\epsilon) = \pi-\epsilon$$

$$\psi_{21}(-\epsilon) = 2\pi-\epsilon$$

$$\psi_{21}(\epsilon) = 2\pi+\epsilon$$

U_1'

REMEMBER, ON $[\epsilon, \pi-\epsilon]$ ψ_{21} DOES NOT EVEN HAVE TO MAKE SENSE!

$$\psi_{21}(x) = (2\pi+x)\Theta(\pi/2-x) + x\Theta(x-\pi/2)$$

$$\psi_{21}(x) = \left\{ \begin{array}{l} 2\pi+x \\ x \end{array} \left| \begin{array}{l} x < \epsilon \\ x > \pi-\epsilon \end{array} \right. \right\}$$

ETC.

NOTE,
$$\partial_x \psi_{21} = \Theta(\pi/2-x) + \Theta(x-\pi/2) + (2\pi+x)\delta(\pi/2-x) + x\delta(x-\pi/2)$$

APPARENTLY IT'S NOT SMOOTH! BUT THAT'S OK, B/C ITS DERIVATIVES ARE WELL DEFINED ON $(-\epsilon, \epsilon) \cup (\pi-\epsilon, \pi+\epsilon)$

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REMEMBER THAT M WAS A TOPOLOGICAL SPACE; JUST A SET OF POINTS & SOME SUBSETS.

IF $p \in U_i$, U_i IS CALLED A COÖRDINATE NEIGHBOURHOOD OF p , & $\{U_i, \varphi_i\}$ IS CALLED A CHART.

IF WE WANT TO TALK ABOUT THE COÖRDINATES OF p , WE NEED TO THINK A BIT MORE ABOUT WHAT A COÖRDINATE IS. IN \mathbb{R}^n , WE HAVE COÖRDINATE FUNCTIONS,

$$x^i: \mathbb{R}^n \rightarrow \mathbb{R}$$

WHICH TAKE A POINT

$$x^i: (\dots, 0, 1, 15, -10, 3, \dots) \mapsto 15.$$

\uparrow i^{th}
 \longleftarrow n \longrightarrow

THAT IS, THEY TAKE A POINT IN \mathbb{R}^n & GIVE ITS DISTANCE ALONG THE i^{th} AXIS.

THEN, FOR $p \in U_i \subset M$, WE HAVE THAT ITS COÖRDINATES IN U_i ARE $\{x^j \circ \varphi_i\}$;

$$(x^1 \circ \varphi_i, x^2 \circ \varphi_i, x^3 \circ \varphi_i, \dots, x^n \circ \varphi_i)$$

THIS WAY OF THINKING ABOUT COÖRDINATES, AS LOCALLY DEFINED FUNCTIONS, IS INTRINSIC TO A SCHEME-THEORETIC VIEWPOINT, WHICH I WON'T COVER, IF AT ALL, UNTIL MUCH LATER.

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IN STRING THEORY, BOSONS ARE THOUGHT OF AS COORDINATES ON THE TARGET MANIFOLD X . INTRINSICALLY, HOWEVER, THEY ARE MAPS

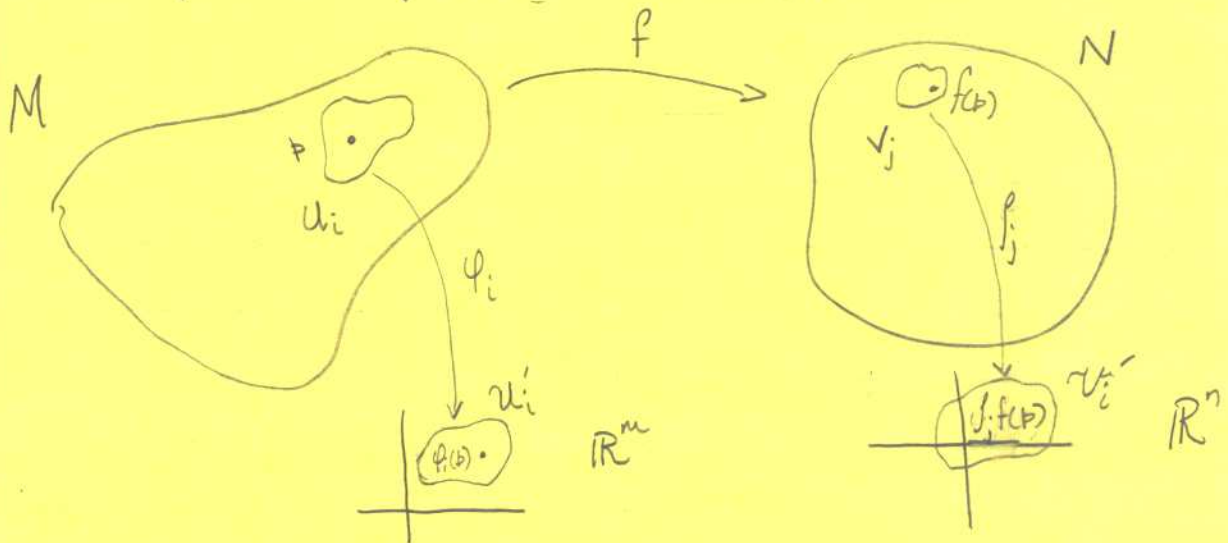
$$\phi: \Sigma \rightarrow X.$$

HOW THEN, DO WE ARRIVE AT THE FAMILIAR FORM

$$\partial_z \phi^{\mu}(z, \bar{z}) \partial_{\bar{z}} \phi^{\nu}(z, \bar{z}) ?$$

LETS CONSIDER THE GENERAL CASE, M & N ARE MANIFOLDS OF RESPECTIVE DIMENSION m & n , &
 $f: M \rightarrow N$.

THEN FOR EACH $p \in M$, WE HAVE $f(p) \in N$



IF U_i & V_j ARE RESPECTIVELY COORDINATE NEIGHBOURHOODS OF p & $f(p)$, THEN WE OBTAIN POINTS

$$\phi_i(p) \in U'_i \subset \mathbb{R}^m \quad \& \quad \psi_j(f(p)) \in V'_j \subset \mathbb{R}^n$$

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By specifying COORDINATE functions
 (x^1, x^2, \dots, x^m) & (y^1, y^2, \dots, y^n)

THE POINTS BECOME $x^i \circ \varphi_i(p)$ & $y^\alpha \circ \beta_j(f(p))$, WHICH
ARE COMMONLY WRITTEN AS

$$\varphi^i(p) \quad \& \quad \beta_j^\alpha(f(p)).$$

WHEN PHYSICISTS ARE WORKING IN A SINGLE COORDINATE
CHART, WE WOULD JUST WRITE φ^i & β^α .

Now, LET'S REWRITE f IN A COMPLICATED WAY:

$$\begin{aligned} p &= \varphi_i^{-1} \circ \varphi_i(p) \\ &= \varphi_i^{-1} \circ x^i(p) \end{aligned}$$

I WRITE "=" HERE BECAUSE THERE ARE A FEW EXTRA STEPS
I'M HIDING, BUT THEY ARE MESSY & THE MEANING SHOULD BE
CLEAR. A GOOD EXERCISE IS TO WORK OUT EXACTLY WHAT
THIS MEANS.

Now, WE CAN WRITE f "IN COORDINATES" AS A MAP
FROM U_i TO V_j

$$(y^\alpha \circ \beta_j) \circ f = \varphi_i^{-1} \circ x^i(p)$$

OR AS PHYSICISTS WOULD WRITE IT, $f^\alpha(x^i)$

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Now, we also want to say when a map $f: M \rightarrow N$ is differentiable:

If $\psi_j \circ f \circ \varphi_i^{-1}: \mathbb{R}^m \rightarrow \mathbb{R}^n$ is an ∞ -diff^{ble} f_{UT}^n in the traditional sense ($\partial_\mu^r f^\alpha(x)$ is def^d $\forall r \geq 0$) for any coordinate charts $U_i \in V_j$, f is smooth.

This is where the magic of the definition of manifolds shines; since ψ_{ij} was ∞ th diff^{ble}, if f is smooth in just one chart, it is smooth in all charts.

We now have a rigorous defⁿ for the physics expression

$$\varphi^M(z, \bar{z})$$

(z & \bar{z} are complex coordinate functions). To understand $\partial_z \varphi^M$, it turns out, will require more machinery: we must understand vector fields.

In physics, we are taught that vectors are objects with indices which transform in a certain way under coordinate transformations. As I was told,

"vectors are things that transform like vectors"

WE WILL TAKE, AT FIRST, A MORE ABSTRACT APPROACH TO VECTORS, & DERIVE THE MORE FAMILIAR FORM.

DEFINITION; A ^{SMOOTH} n FUNCTION ON A MANIFOLD M IS A MAP $f: M \rightarrow \mathbb{R}^n$, THAT IS, A SMOOTH ASSIGNMENT OF