

Def: Let  $\vec{b} = (b_1, b_2, \dots, b_\ell) \in \mathbb{Z}^\ell$ , set

$$\phi(z) = \frac{z_1^{b_1} z_2^{b_2} \dots z_\ell^{b_\ell}}{(1 - q_1 \frac{z_1}{z_2}) \dots (1 - q_\ell \frac{z_\ell}{z_1})}$$

Laurent poly.      Not a Laurent poly.

By Negut (2014) (The shuffle algebra revisited), there exists a Laurent polynomial  $v(z) = v(z_1, \dots, z_\ell)$  s.t.  $\text{Hg}_{q_i}^\ell(v(z)) = \text{Hg}_{q_i}^\ell(\phi(z))$  and  $v(z)$  represents a well-defined element of the shuffle algebra  $S$ .

The **Negut element**  $D_{\vec{b}}$  and the **transposed Negut element**  $E_{\vec{a}}$  (where  $\vec{a} := \text{rev}(\vec{b}) = (b_\ell, b_{\ell-1}, \dots, b_1)$ ) are defined by

$$D_{\vec{b}} = D_{b_1 b_2 \dots b_\ell} = \psi(v(z)) \in \mathcal{E}^+$$

$$E_{\vec{a}} = E_{b_\ell b_{\ell-1} \dots b_1} := \Phi(D_{\vec{b}}) = \psi^{\text{op}}(v(z)) \in \Phi \mathcal{E}^+$$

Recall:

Prop 3.4.1 (Schiffmann, Vasserot 2013) There is an algebra isomorphism  $\psi: S \rightarrow \mathcal{E}^+$  and anti-isomorphism  $\psi^{\text{op}} = \Phi \circ \psi: S \rightarrow \Phi \mathcal{E}^+$   
 $z^a \mapsto p_i[-MX^{a_i}]$        $z^a \mapsto p_i[-MX^{a_i}]$

\* On monomials in  $m$  variables, representing elements of tensor degree  $m$  in  $S$ ,

$$\psi(z_1^{a_1} z_2^{a_2} \dots z_m^{a_m}) = p_1[-MX^{a_1}] \dots p_m[-MX^{a_m}]$$

$$\psi^{\text{op}}(z_1^{a_1} z_2^{a_2} \dots z_m^{a_m}) = p_m[-MX^{a_m}] \dots p_1[-MX^{a_1}]$$

Prop 3.4.2 (Path Prop 3.5.2) Let  $\phi(z) = \phi(z_1, z_2, \dots, z_\ell)$  be a Laurent polynomial representing an element of tensor degree  $\ell$  in  $S$ .

Let  $\zeta = \psi(\phi(z)) \in \mathcal{E}^+$ .

With  $\mathcal{E}$  acting on  $\Lambda$  as in Prop 3.3.1, we have

$$\omega(\zeta \cdot 1)(z_1, z_2, \dots, z_\ell) = \text{Hg}_{q_i}^\ell(\phi(z))_{\text{pol.}}$$

e.g. Set  $\ell = 1$ . Let  $b \in \mathbb{Z}$ .

Then  $\phi(z) = z^b$ . Hence we can take  $v(z) = z^b$  and hence  $D_{\vec{b}} = \psi(z^b) = p_1[-MX^{b_1}]$  and  $E_{\vec{b}} = \psi^{\text{op}}(z^b) = p_1[-MX^{b_1}]$

\* Hence  $D_{\vec{b}}$  and  $E_{\vec{b}}$  acts on  $\Lambda$  as  $D_b$  and  $E_b$  respectively when  $\ell(\vec{b}) = 1$  (by Prop 3.3.3).

Negut identifies certain  $D_{\vec{b}}$  as ribbon skew Schur functions. Here is a special case:

Prop 3.6.1 (Path):

- $m, k \in \mathbb{I}^+$ ,  $n \in \mathbb{Z}_{\geq 0}$

- $\text{gcd}(m, n) = 1$

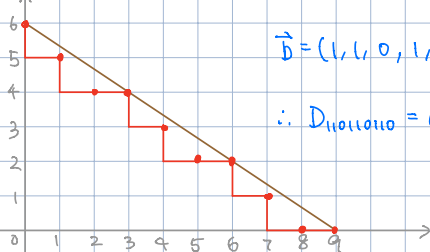
- $b_i = \lfloor \frac{m}{n} i \rfloor - \lfloor \frac{m}{n} (i-1) \rfloor$  (# south steps at  $x=i-1$  in the highest SE path weakly below  $y = -\frac{m}{n}x + kn$ )

Then

$$D_{b_1 b_2 \dots b_{kn}} = e_k[-MX^{m, n}]$$

i.e. x-intercept:  $(kn, 0)$   
y-intercept:  $(0, kn)$

e.g.  $(m, n) = (3, 2)$ ,  $k = 3$



$$\vec{b} = (1, 1, 0, 1, 1, 0, 1, 1, 0)$$

$$\therefore D_{110110110} = e_3[-MX^{3, 2}]$$

Lemma 3.6.2 (Path): For any indices  $b_1, \dots, b_\ell \in \mathbb{Z}$ , we have

$$D_{b_1, b_2, \dots, b_\ell, 0} \cdot 1 = D_{b_1, b_2, \dots, b_\ell} \cdot 1 \quad (\text{i.e. we can omit trailing zeros when acting on } 1)$$

\* We have an E-version which we will prove later in §4.3

Proof: By Prop 3.4.2 (above),  $\omega(D_{b_1, \dots, b_\ell} \cdot 1)(x_1, \dots, x_\ell) = \text{Hgt} \left( \frac{x_1^{b_1} x_2^{b_2} \dots x_\ell^{b_\ell}}{\prod_{i=1}^{\ell} (1 - qt \frac{x_i}{x_{i+1}})} \right)_{\text{pol}}$  which is a linear combination of  $s_\lambda$  with  $|\lambda| \leq \ell$ .

$$\begin{aligned} \omega(D_{b_1, \dots, b_\ell, 0} \cdot 1)(x_1, \dots, x_{\ell+1}) &= \text{Hgt} \left( \frac{x_1^{b_1} \dots x_\ell^{b_\ell} x_{\ell+1}^0}{\prod_{i=1}^{\ell+1} (1 - qt \frac{x_i}{x_{i+1}})} \right)_{\text{pol}} \\ &= \text{Hgt} \left( \frac{x_1^{b_1} \dots x_\ell^{b_\ell}}{\prod_{i=1}^{\ell} (1 - qt \frac{x_i}{x_{i+1}})} \right)_{\text{pol}} \\ &= \text{Hgt} \left( \frac{x_1^{b_1} \dots x_\ell^{b_\ell}}{\prod_{i=1}^{\ell} (1 - qt \frac{x_i}{x_{i+1}})} \cdot \underbrace{\left( 1 + qt \frac{x_\ell}{x_{\ell+1}} + qt^2 \frac{x_\ell^2}{x_{\ell+1}^2} + \dots \right)}_{\substack{\text{we can drop these} \\ \text{because we only} \\ \text{take "polynomial" parts} \\ \leftarrow \text{ie. } x_i \text{ with} \\ \text{a poly. weight} \\ \text{(constant)}}} \right)_{\text{pol}} \end{aligned}$$

which is a linear combination of Schur functions  $s_\lambda$  with  $|\lambda| \leq \ell$

$$\therefore \omega(D_{b_1, \dots, b_\ell, 0} \cdot 1)(x_1, \dots, x_\ell) = \omega(D_{b_1, \dots, b_\ell} \cdot 1)(x_1, \dots, x_\ell) \quad \square$$

Hence a corollary to Prop 3.6.1 is  $D_{b_1, \dots, b_{k-1}, \underbrace{b_k}_{\substack{\uparrow \\ \text{this is always 0}}}} \cdot 1 = e_k[-MX^{m, m}] \cdot 1$

Also, in the example above,  $D_{1, 0, 1, 1, 0, 1, 0, 0} \cdot 1 = e_3[-MX^{3, 2}] \cdot 1$  and  $D_{1, 0, 1, 1, 0, 1, 1} \cdot 1 = e_3[-MX^{3, 2}] \cdot 1$

Corollary: If  $n=1$ , we have  $\nabla^m e_n(x) = e_k[-MX^{m, 1}] \cdot 1$ .

Proof:  $e_k[-MX^{0, 1}] \cdot 1 = e_k(x)$  and  $\nabla(1) = 1$   
By Prop 3.3.1 (iii)

$$\therefore e_k[-MX^{m, 1}] = \nabla^m e_k[-MX^{0, 1}] \nabla^{-m} \Rightarrow e_k[-MX^{m, 1}] \cdot 1 = \nabla^m e_k[-MX^{0, 1}] \nabla^{-m} \cdot 1 = \nabla^m e_k[-MX^{0, 1}] \cdot 1 = \nabla^m e_k(x) \quad \square$$

\* Prop 3.4.2 implies  $\omega(\nabla^m e_{k+1})(x_1, \dots, x_\ell) = \omega(e_{k+1}[-MX^{m, 1}] \cdot 1)(x_1, \dots, x_\ell)$

raising operator formula  $\rightarrow$

$$\begin{aligned} &= \omega(D_{\underbrace{0}_{\substack{\uparrow \\ \text{this is always 0}}}} \cdot 1)(x_1, \dots, x_\ell) \\ &= \text{Hgt} \left( \frac{x_1^0}{\prod_{i=1}^{\ell} (1 - qt \frac{x_i}{x_{i+1}})} \right)_{\text{pol}} \\ &= \nabla \left( \frac{x_1 x_{k+1} x_{k+2} \dots x_{k+m} \prod_{i=1, i \neq k}^{\ell} (1 - qt \frac{x_i}{x_{i+1}})}{\prod_{i=1, i \neq k}^{\ell} (1 - qt \frac{x_i}{x_{i+1}}) (1 - t \frac{x_k}{x_{k+1}})} \right)_{\text{pol}} \end{aligned}$$

$\vec{b} = (1, 0, 0, \dots, 0, 1, 0, 0, \dots, 1, 0, 0, \dots, 0, \dots, 1, 0, 0, \dots, 0)$   
 ie "1, 0, 0, ..., 0"s  
 $b_1 = b_{k+1} = b_{k+2} = \dots = b_{k+m} = 1$  and all other  $b_j$ 's are 0.

$$= \left( \sum_{w \in S_\ell} w \left( \frac{x_1 x_{k+1} x_{k+2} \dots x_{k+m} \prod_{i=1, i \neq k}^{\ell} (1 - qt \frac{x_i}{x_{i+1}})}{\prod_{i=1, i \neq k}^{\ell} (1 - qt \frac{x_i}{x_{i+1}}) (1 - t \frac{x_k}{x_{k+1}}) (1 - t \frac{x_k}{x_i})} \right) \right)_{\text{pol}}$$

for any  $\ell \geq k+m+1$   
 ie we only take "pol"

Useful identities: (1)  $D_{b_1, \dots, b_\ell} D_{b_{\ell+1}, \dots, b_n} = D_{b_1, b_2, \dots, b_n} - qt D_{b_1, \dots, b_{\ell+1}, b_{\ell+1}, b_{\ell+2}, \dots, b_n}$

for any indices  $a_1, \dots, a_n, b_1, \dots, b_n \in \mathbb{Z}$ .

(2)  $E_{a_1, \dots, a_{\ell+1}} E_{a_\ell, \dots, a_1} = E_{a_1, \dots, a_\ell} - qt E_{a_1, \dots, a_{\ell+1}, a_{\ell+1}, a_{\ell+2}, \dots, a_1$

e.g. We can write  $D_{3,2} \cdot 1$  in terms of  $(D_a D_b \cdot 1)$ 's and  $(D_a \cdot 1)$ 's (i.e. in terms of  $D$ 's with indices in  $\mathbb{Z}$  instead of vectors in  $\mathbb{Z}^d$  with  $d \geq 2$ )

$$D_{a,-1} - q^t D_{3,-a} = D_a D_{-1} \Rightarrow D_{3,-a} = \frac{1}{q^t} (D_{a,-1} - D_a D_{-1})$$

Similarly,  $D_{a,-1} = \frac{1}{q^t} (D_{1,0} - D_1 D_0)$

$$\therefore D_{3,-2} = \frac{1}{q^{2t}} D_{1,0} - \frac{1}{q^{2t}} D_1 D_0 - \frac{1}{q^t} D_2 D_{-1}$$

$$\text{Hence } D_{3,a} \cdot 1 = \frac{1}{q^{at}} D_{1,0} \cdot 1 - \frac{1}{q^{at}} D_1 D_0 \cdot 1 - \frac{1}{q^t} D_2 D_{-1} \cdot 1$$

$$= \frac{1}{q^{at}} D_1 \cdot 1 - \frac{1}{q^{at}} D_1 D_0 \cdot 1 - \frac{1}{q^t} D_2 D_{-1} \cdot 1$$



$$\frac{1}{q^{at}} p_1[-MX^{a,1}] \cdot 1 - \frac{1}{q^{at}} p_1[-MX^{a,1}] p_1[-MX^{1,0}] \cdot 1 - \frac{1}{q^t} p_1[-MX^{1,2}] p_1[-MX^{1,-1}] \cdot 1$$

Lemma 4.1.a. Let  $\phi(z)$  be a Laurent polynomial representing an element of tensor degree  $n$  in  $S$ . Then

$$(\text{Ad}f(X^{1,0})) \psi^{\text{op}}(\phi(z)) = \psi^{\text{op}}((\omega f)(z_1, z_2, \dots, z_n) \cdot \phi(z))$$

In particular, we have

$$(\text{Ad}f(X^{1,0})) E_{a_1, \dots, a_n} = \psi^{\text{op}} \left( \frac{(\omega f)(z_1, \dots, z_n) \cdot z_1^{a_1} z_2^{a_2} \dots z_n^{a_n}}{\prod_{i=1}^n (1 - q^t \frac{z_i}{z_{i+1}})} \right)$$

Take  $\phi(z) = \frac{z_1^{a_1} \dots z_n^{a_n}}{\prod_{i=1}^n (1 - q^t \frac{z_i}{z_{i+1}})}$

e.g.  $\text{Ad}f(X^{1,0}) \psi^{\text{op}}(z_1^a z_2^b) = \text{Ad}f(X^{1,0}) (p_1[-MX^{b,1}] p_1[-MX^{a,1}])$

$$= \sum_i (\text{Ad}f_{(i)}(X^{1,0}) p_1[-MX^{b,1}]) (\text{Ad}f_{(i)}(X^{1,0}) p_1[-MX^{a,1}])$$

$$= \sum_i (-M)^a (\omega f_{(i)}[z]) \Big|_{z^k \mapsto p_1(X^{b+k,1})} \omega f_{(i)}[z] \Big|_{z^k \mapsto p_1(X^{a+k,1})}$$

Note:  $g(z) \Big|_{z^k \mapsto p_1(-MX^{a+k,1})} = -M g(z) \Big|_{z^k \mapsto p_1(X^{a+k,1})}$

$$= \sum_i (\omega f_{(i)}[z_2]) \Big|_{z^k \mapsto p_1(-MX^{b+k,1})} z_1^a \omega f_{(i)}[z_1] \Big|_{z^k \mapsto p_1(-MX^{a+k,1})}$$

Note: for any  $g \in \mathbb{C}[z]$

$$g(z) \Big|_{z^k \mapsto p_1(X^{b+k,1})} = (z^b g(z)) \Big|_{z^k \mapsto p_1(X^{k,1})}$$

e.g.  $g(z) = z^3$

Then  $g(z) \Big|_{z^k \mapsto p_1(X^{b+k,1})} = p_1(X^{b+3,1})$

$$(z^b g(z)) \Big|_{z^k \mapsto p_1(X^{k,1})}$$

$$= (z^{b+3}) \Big|_{z^k \mapsto p_1(X^{k,1})} = p_1(X^{b+3,1})$$

$$= (z_1^a z_2^b (\omega f)(z_1, z_2)) \Big|_{z_1^k, z_2^k \mapsto p_1(-MX^{k+1,1})}$$

$$= \psi^{\text{op}}((\omega f)(z_1, z_2) z_1^a z_2^b) \quad (\text{The proof basically follows the same idea.})$$

e.g.  $z^3 \Big|_{z^k \mapsto p_1(-MX^{a+k,1})} = p_1[-MX^{a+3,1}] + p_1[-MX^{a+2,1}] = -M p_1(X^{a+2,1}) - M p_1(X^{a+1,1}) = -M(z^3 z^2) \Big|_{z^k \mapsto p_1(X^{a+k,1})}$