# Math 240: Matrix Operations and Linear Systems 

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## Outline

(1) Review of Last Time

(2) Matrix Operations

## (3) Systems of Linear Equations

## A Quick Review

## Definition

A matrix is a rectangular array of numbers or functions
$\left(\begin{array}{lll}1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9\end{array}\right)$

Matrix Operations

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(2) Scalar Multiplication: $k\left(a_{i j}\right)_{m \times n}=\left(k a_{i j}\right)_{m \times n}$
(3) Matrix multiplication: The ij entry is the dot product of the i-th row of the matrix on the left with the $j$-th column of the matrix on the right.

## Finishing Matrix Operations

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Performed: Rows of $A$ become columns of $A^{T}$ and columns of $A$ become rows of $A^{T}$.

## Special Matrices

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## Definition

The identity matrix of dimension $n$, denoted $I_{n}$, is the $n \times n$ diagonal matrix where all the diagonal entries are 1 .

## Matrix Properties

Let $A$ and $B$ be $m \times n$ matrices. Let $k$ and $p$ be scalars.
(1) $A+B=B+A$
(2) $A+(B+C)=(A+B)+C$
(3) $k(A+B)=k A+k B$
(9) $(k+p) A=k A+p A$

Let 0 be the $m \times n$ matrix of all zeros
(1) $A+0=A$
(2) $A-A=0$
(3) $k A=0$ implies $k=0$ or $A=0$.

## More Matrix Properties

(1) $A(B C)=(A B) C$
(2) $A(B+C)=A B+A C$
(3) $(A+B) C=A C+B C$
(9) $k(A B)=(k A) B=A(k B)$
(5) $I_{m} A=A$
(3) $A I_{n}=A$

## Even More Matrix Properties

(1) $\left(A^{T}\right)^{T}=A$
(2) $(k A)^{T}=k A^{T}$
(3) $(A+B)^{T}=A^{T}+B^{T}$
(9) $(A B)^{T}=B^{T} A^{T}$

## Systems of Linear Equations

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Linear systems are essential to finding quantatative or approximate solutions to any problem that can be stated mathematically

## Solutions to linear systems

Not every linear system has a unique solution.

## Definition

A linear system is called consistent if it has a solution, it is called inconsistent if it does not have a solution.

There are three possibilities:
(1) The system has $\infty$-many solutions.
(2) The system has a unique solution.
(3) The system has no solution.

## Solving a linear system

The standard way is to use elementary operations to isolate each variable.

The elementary operations are:
(1) Multiply an equation by a non-zero constant.
(2) Add a non-zero multiple of one equation to another.

## Echelon Forms

## Definition

A matrix is in row-echelon form if
(1) Any row consisting of all zeros is at the bottom of the matrix.
(2) For all non-zero rows the leading entry must be a one. This is called the pivot.
(3) In consecutive rows the pivot in the lower row appears to the right of the pivot in the higher row.

## Definition

A matrix is in reduced row-echelon form if it is in row-echelon form and every pivot is the only non-zero entry in its column.

## Row Operations

We will be applying row operations to augmented matrices to find solutions to linear equations. This is called Gaussian or Gauss-Jordan elimination.

Here are the row operations:
(1) Multiply a row by a number.
(2) Switch rows.
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Key Fact: If you alter an augmented matrix by row operations you preserve the set of solutions to the linear system.

