Math 240: Linear Differential Equations

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Outline

Today's Goals

Understand the form of solutions to the following types of higher order, linear differential equations

- Initial Value Problems
- Boundary Value Problems
- Momogeneous and Nonhomogeneous Equations.

A Few Famus Differential Equations

- Einstein's field equation in general relativity
- The Navier-Stokes equations in fluid dynamics
- Verhulst equation biological population growth
- The Black-Scholes PDE models financial markets

Higher Order Initial Value Problems

Definition

For a linear differential equation, an nth-order initial value problem(IVP) is

Solve:
$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + ... a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

Subject to:
$$y(x_0) = y_0$$
, $y'(x_0) = y_1$, ..., $y^{(n-1)}(x_0) = y_{n-1}$

Existence and Uniqueness

Theorem

Let $a_n(x)$, $a_{n-1}(x)$, ..., $a_1(x)$, $a_0(x)$, and g(x) be continuous on and interval I, and let $a_n(x) \neq 0$ for every x in this interval. If $x = x_0$ is any point in this interval, then a solution y(x) of the initial value problem exists on the interval and is unique.

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Example: Does the following IVP have a unique solution? If so, on what intervals?

$$y''' + y'' - y' - y = 9$$
 with $y(2) = 0$, $y'(2) = 0$ and $y''(2) = 0$

Boundary Value Problem

Definition

For a linear differential equation, an **nth-order boundary value problem**(BVP) is

Solve:
$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + ... a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

Subject to n equations that specify the value of y and its derivatives at **different** points (called **boundary conditions**).

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Question: What are the possible boundary conditions for a second order linear D.F.

One, Many or No Solutions

A BVP may have one, ∞ -many, or no solutions.

Example:
$$x'' + 16x = 0$$

Homogeneous and Nonhomogeneous

Definition

An nth-order differential equation of the following form is said to be **homogeneous**. Otherwise we say the equation is **nonhomogeneous**.

Solve:
$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + ... a_1(x)\frac{dy}{dx} + a_0(x)y = 0$$

Using Linearity to Find More Solutions

Theorem

(The Superposition Principle) Let $y_1, y_2, ... y_k$ be solutions to a homogeneous nth-order differential equation on an interval I. Then any linear combination

$$y = c_1 y_1(x) + c_2 y_2(x) + ... + c_k y_k(x)$$

is also a solution, where $c_1, c_2, ..., c_k$ are constants.

Linear Independence of Functions

Definition

A set of functions $f_1(x), f_2(x), ..., f_n(x)$ is **linearly dependent** on an interval I is there exists constants $c_1, c_2, ..., c_n$, not all zero, such that

$$c_1 f_1(x) + c_2 f_2(x) + ... + c_n f_n(x) = 0$$

for every x in the interval. A set of functions that is not linearly dependent is said to be **Linearly Independent**.

The Wronskian

Definition

Suppose each of the functions $f_1(x)$, $f_2(x)$, ..., $f_n(x)$ possess at least n-1 derivatives. The determinant

$$W(f_1, f_2, ..., f_n) = \begin{vmatrix} f_1 & f_2 & ... & f_n \\ f'_1 & f'_2 & ... & f'_n \\ \vdots & \vdots & & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & ... & f_n^{(n-1)} \end{vmatrix}$$

is called the Wronskian of the functions.

Linearly Independent Solutions

Theorem

Let $y_1, y_2, ..., y_n$ be n solutions to a homogeneous linear nth-order differential equation on an interval I. The the set of solutions is **linearly independent** on I if and only if $W(y_1, y_2, ..., y_n) \neq 0$ for every x in the interval. If the solutions $y_1, y_2, ..., y_n$ are linearly independent they are said to be a **fundamental set of solutions**.

Note: There always exists a fundamental set of solutions to an nth-order linear homogeneous differential equation on an interval *I*.

General Solution

Theorem

Let $y_1, y_2, ..., y_n$ be a fundamental set of solutions set of solutions to an nth-order linear homogeneous differential equation on an interval I. Then the general solution of the equation on the interval is

$$y = c_1 y_1(x) + c_2 y_2(x) + ... + c_n y_n(x)$$

where the c_i are arbitrary constants.

General Solutions to Nonhomogeneous Linear D.E.s

Theorem

Let y_p be any particular solution of the nonhomogeneous linear nth-order differential equation on an interval I. Let $y_1, y_2, ..., y_n$ be a fundamental set of solutions to the associated homogeneous differential equation. Then the general solution to the nonhomogeneous equation on the interval is

$$y = c_1 y_1(x) + c_2 y_2(x) + ... + c_n y_n(x) + y_p$$

where the c_i are arbitrary constants.

Superposition Principle for Nonhomogeneous Equations

Theorem

Suppose y_{p_i} denotes a particular solution to the differential equation

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + ... a_1(x)\frac{dy}{dx} + a_0(x)y = g_i(x)$$

Where i = 1, 2, ..., k. Then $y_p = y_{p_1} + y_{p_2} + ... + y_{p_k}$ is a particular solution of

$$a_n(x)\frac{d^n y}{dx^n} + a_{n-1}(x)\frac{d^{n-1} y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y =$$

$$g_1(x) + g_2(x) + \dots + g_k(x)$$