Math 240: Vector Calc. Review

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Thursday March 3, 2011

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Outline





- ③ Vector-Valued Functions
- 4 Del, Div, Curl, Grad

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Review

Review for Last Time

- Learned how to model spring/mass systems with damped motion.
- **2** Learned how to model spring/mass systems with driven motion.

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Suppose 16 N of force stretches a spring 1 meter from equilibrium. If a mass of 4 kg is attached to the spring and subjected to a driving force given by f(t) = cos(t), then find the equation that models the position of the system in the absence of a damping force.

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Today's Goals

- Review vector valued functions.
- Review del, grad, curl and div.
- Review line integrals.

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Vector-Valued Functions

Definition

Vectors whose components are functions of a parameter *t* are called **vector-valued** functions.

$$r(t) = \langle f(t), g(t) \rangle = f(t)\mathbf{i} + g(t)\mathbf{j}$$

$$r(t) = \langle f(t), g(t), h(t) \rangle = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{i}$$

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Example: $r(t) = \langle cos(t), sin(t), t \rangle$

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Example: r(t) = < cos(t), sin(t), t >**Important:** These are the parameterized curves we will integrate along

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Derivative of a Vector-Valued Function

Definition

If $r(t) = \langle f(t), g(t), h(t) \rangle$ where f, g, and h are differentiable, then

$$r^{\prime}(t)=< f^{\prime}(t),g^{\prime}(t),h^{\prime}(t)>$$

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Theorem

(Chain Rule) If **r** is a differentiable vector function and s = u(t) is a differentiable scalar function, then

$$rac{d\mathbf{r}}{dt} = rac{d\mathbf{s}}{ds}rac{ds}{dt} = \mathbf{r}'(s)u'(t).$$

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Integrating Vector-Valued Functions

Theorem

If f, g and h are integrable and $r(t) = \langle f(t), g(t), h(t) \rangle$, then

$$\int \mathbf{r}(t)dt = <\int f(t)dt, \int g(t)dt, \int h(t)dt >$$
$$\int_{a}^{b} \mathbf{r}(t)dt = <\int_{a}^{b} f(t)dt, \int_{a}^{b} g(t)dt, \int_{a}^{b} h(t)dt >$$

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The differential operator **del** is given by

$$\nabla = \frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}$$

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The differential operator **del** is given by

$$\nabla = \frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}$$

Given a scalar function f(x, y, z) we can form the **gradient of f** using del.

$$grad(f) = \nabla f = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}$$

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 ∇f points in the direction of greatest change of f. **Example:** Guess the gradient of f(x, y, z) = xyz at (1, 1, 1) by interpreting the function as volume of a box.

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Div and Curl

Definition

The **curl** of a vector field $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ is the vector field

$$curl(F) = \nabla \times F = \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}\right)\mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}\right)\mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\mathbf{k}$$

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Definition

The **divergence** of a vector field $F = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$ is given by the scalar function

$$div(F) = \nabla \dot{F} = \frac{\partial P}{\partial x}\mathbf{i} + \frac{\partial Q}{\partial y}\mathbf{j} + \frac{\partial R}{\partial z}\mathbf{k}$$

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Curl measures the tendency of a vector field to rotate. Divergence measures the tendency of a vector field to expand or contract.

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Compositions

It is important to note

- grad(scalar function) = vector field
- \bigcirc div(vector field) = scalar function
- surl(vector field) = vector field

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Line Integrals in 2D

If G(x,y) is a scalar valued function and C is a smooth curve in the plane defined by the parametric equations x = f(t) and y = g(t)where a < t < b then we can define the following line integrals

•
$$\int_C G(x, y) dx = \int_a^b G(f(t), g(t)) f'(t) dt$$

•
$$\int_C G(x, y) dy = \int_a^b G(f(t), g(t)) g'(t) dt$$

•
$$\int_C G(x,y)ds = \int_a^b G(f(t),g(t))\sqrt{(f'(t))^2 + (g'(t))^2}dt$$

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Line Integrals in 3D

If G(x,y,z) is a scalar valued function and C is a smooth curve in 3-space defined by the parametric equations x = f(t), y = g(t) and z = h(t) where $a \le t \le b$ then we can define the following line integrals