

# LINEAR ALGEBRA

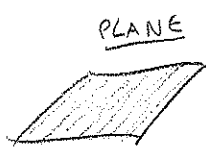
SUPPOSE WE WANTED TO SOLVE A SYSTEM OF EQUATIONS

$$3x + y + z = 5$$

$$x + 3y - z = 3$$

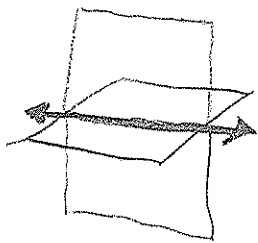
$$-x - y + z = -1$$

THESE EQ'S ARE CALLED LINEAR SINCE THEY ONLY INVOLVE SCALAR MULTIPLES OF THE VARIABLES AND CONSTANTS. DO SOLUTIONS EXIST? IF SO, WHAT ARE THEY? WE CAN PICTURE OUR SOLUTION IN 3-SPACE AS THE INTERSECTION OF 3 PLANES. OUR SET OF SOLUTIONS TO THESE EQ'S CAN LOOK LIKE ONLY ONE OF A FEW THINGS:



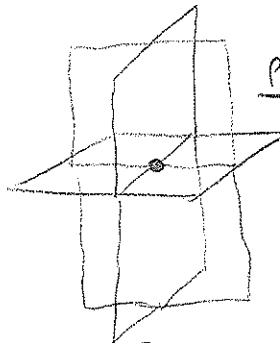
PLANE

2-D



LINE

1-D



POINT

0-D



NONE

(PLANES ARE PARALLEL)

EACH OF THESE SOLUTION SPACES HAS A DIMENSION WE CAN ASSOCIATE TO IT SINCE WE CAN PICTURE IT.

- HOW DO WE DEFINE THIS DIMENSION FOR MORE VARIABLES? (WE CAN'T PICTURE IT ANYMORE!)
- HOW CAN WE FIND THIS DIMENSION GIVEN JUST OUR EQ'S AND NOT HAVING TO DRAW PICTURES?

THIS IS THE START OF LINEAR ALGEBRA.

FIRST, SOME NOTATION.

$\mathbb{R}$  - REAL NUMBERS

$\mathbb{Z}$  - INTEGERS  $\{0, \pm 1, \pm 2, \dots\}$

$\mathbb{Q}$  - RATIONAL NUMBERS (FRACTIONS)

$\mathbb{C}$  - COMPLEX NUMBERS  $\{a+ib \mid a, b \in \mathbb{R}\}$

THIS IS READ AS:

THE SET OF  $\left\{ \begin{array}{l} \text{ALL } a+ib \\ a+ib \end{array} \right\}$  SUCH THAT  $\left\{ \begin{array}{l} \text{A AND } b \text{ ARE ELEMENTS OF THE REALS} \\ a, b \in \mathbb{R} \end{array} \right\}$

$\mathbb{R}^2$  - SET OF ALL POINTS  $(x, y)$  IN 2-SPACE

$\mathbb{R}^n$  - " "  $(x_1, x_2, \dots, x_n)$  IN  $n$ -SPACE

s.t. - "SUCH THAT"

$A \implies B$  - STATEMENT A IMPLIES STATEMENT B

$A \iff B$  - STATEMENT A IFF STATEMENT B

IFF - IF AND ONLY IF

## VECTORS IN $\mathbb{R}^2$

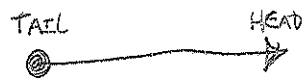
WE THINK OF VECTORS IN  $\mathbb{R}^2$  AS PAIRS OF REAL NUMBERS  $(x, y)$  SUCH THAT WE ADD THEM COMPONENTWISE:

$$(1, 1) + (3, 0) = (1+3, 1+0) = (4, 1)$$

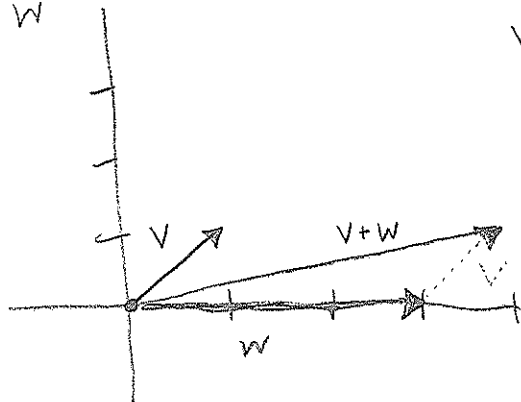
↓  
V

↑  
W

↑  
V+W



PICTORALLY:



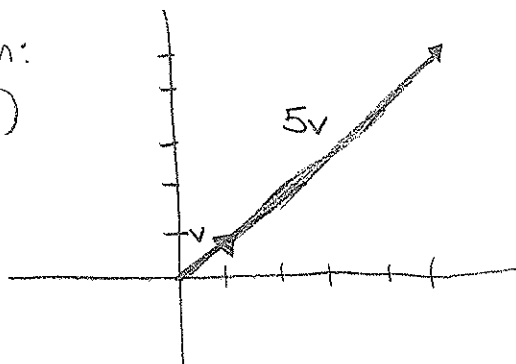
WE CAN ADD V TO W BY MOVING THE TAIL OF V TO THE HEAD OF W.

WE CAN SCALE THEM:

$$5(1, 1) = (5, 5)$$

↓  
V

↑  
5V



WE CAN DO THE SAME THING FOR  $\mathbb{R}^n$  w/ OPERATIONS:

$$(x_1, \dots, x_n) + (y_1, \dots, y_n) = (x_1 + y_1, \dots, x_n + y_n)$$

$$c(x_1, \dots, x_n) = (cx_1, \dots, cx_n)$$

THE SPACES  $\mathbb{R}^n$  THUS FORM A VECTOR SPACE. A VECTOR SPACE CONSISTS OF A SET OF OBJECTS  $v \in V$  SUCH THAT:

- ① IF  $v, w \in V$ ,  $v+w \in V$  (WE CAN ADD THEM)
- ② IF  $v \in V$ ,  $cv \in V$  FOR  $c \in \mathbb{R}$  (WE CAN SCALE THEM)
- ③ THERE IS A ZERO VECTOR  $0$  SUCH THAT  $0+v = v$  FOR ALL  $v$ .

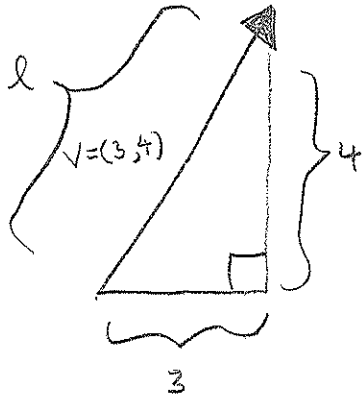
## DOT PRODUCTS

FOR TWO VECTORS  $\overset{V}{\parallel} (x_1, \dots, x_n)$  AND  $\overset{W}{\parallel} (y_1, \dots, y_n) \in \mathbb{R}^n$ , THE DOT PRODUCT IS:

$$V \cdot W = x_1 y_1 + x_2 y_2 + \dots + x_n y_n$$

EX:  $(1, 2) \cdot (3, 4) = (1)(3) + (2)(4) = 11$

THE LENGTH OF A VECTOR  $(3, 4)$  IS JUST  $\sqrt{3^2 + 4^2} = 5$  BY PYTHAG:



$$4^2 + 3^2 = l^2$$

$$25 = l^2$$

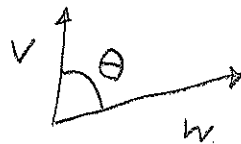
$$\underline{5 = l}$$

IN GENERAL, THE LENGTH OF A VECTOR  $\overset{V}{\parallel} (x_1, \dots, x_n) \in \mathbb{R}^n$  IS DENOTED  $\|V\|$  AND IS CALCULATED:  $\|V\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$

### KEY PROPERTY OF $\cdot$

FOR TWO VECTORS  $V, W$  IN  $\mathbb{R}^2$  OR  $\mathbb{R}^3$ ,

$$V \cdot W = \|V\| \|W\| \cos \theta$$

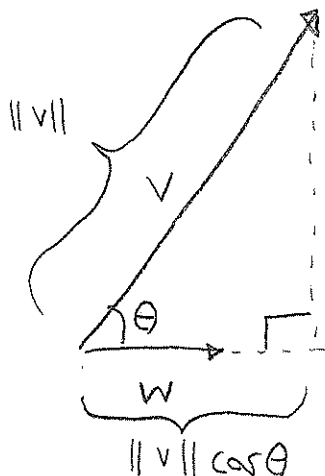


WHERE  $\theta$  = ANGLE BETWEEN THEM

SO IF  $W$  IS A UNIT VECTOR (THIS MEANS  $\|W\| = 1$ ) WE HAVE:

$$V \cdot W = \|V\| \cos \theta$$

BUT BY TRIG, THIS NUMBER HAS A GEOMETRIC INTERPRETATION:



THIS  $V \cdot W$  IS THE LENGTH OF COMPONENT OF  $V$  IN THE DIRECTION OF  $W$  (CALLED THE PROJECTION ALONG  $W$ )

IN  $\mathbb{R}^3$ , WE OFTEN USE THE NOTATION

$$(1, 0, 0) = \hat{i} \quad (0, 1, 0) = \hat{j} \quad (0, 0, 1) = \hat{k} \quad \text{FOR SHORTHAND}$$

IN  $\mathbb{R}^n$ , WE OFTEN USE

$$(1, 0, 0, \dots, 0) = e_1 \quad (0, 1, 0, \dots, 0) = e_2 \quad \dots \quad (0, 0, \dots, 0, 1) = e_n$$

### CROSS PRODUCTS (ONLY IN $\mathbb{R}^3$ )

SUPPOSE  $V = (1, 2, 3)$   $W = (4, 5, 6)$

THEIR CROSS PRODUCT IS COMPUTED:

$$\begin{aligned} V \times W &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{vmatrix} = \begin{vmatrix} 2 & 3 \\ 5 & 6 \end{vmatrix} \hat{i} - \begin{vmatrix} 1 & 3 \\ 4 & 6 \end{vmatrix} \hat{j} + \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} \hat{k} \\ &= (12 - 15) \hat{i} - (6 - 12) \hat{j} + (5 - 8) \hat{k} \\ &= -3\hat{i} + 6\hat{j} - 3\hat{k} \\ &= (-3, 6, -3) \end{aligned}$$

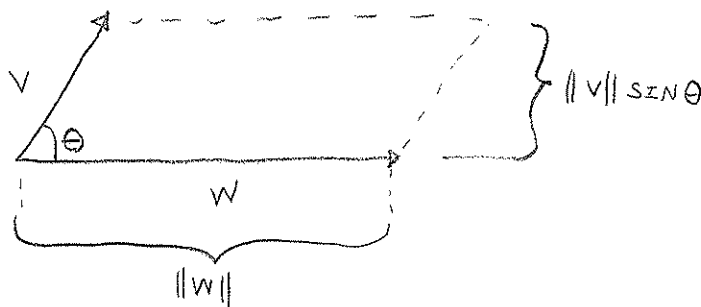
HERE  $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$  IS THE 2x2 DETERMINANT (WE'LL GET TO THIS LATER)

IT SATISFIES:

$$\|V \times W\| = \|V\| \|W\| \sin \theta \quad \text{AND} \quad V \times W \text{ IS PERPENDICULAR TO BOTH } V \text{ AND } W$$

GEOMETRICALLY:

IT IS THE AREA OF THE PARALLELOGRAM GIVEN BY THE VECTORS.



NOTATION: IN  $\mathbb{R}^n$ , WE WILL WRITE OUR VECTORS AS COLUMN VECTORS AS WELL. SO  $(1, 2) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ ,  $(1, 2, 3) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$  ETC.

DEF: A LINEAR COMBINATION OF THE VECTORS  $v_1, \dots, v_n$  IS ANY VECTOR OF THE FORM  $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = \sum_{i=1}^n c_i v_i$ .

EX: A LINEAR COMBINATION (L.C. FROM NOW ON) OF  $v = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  AND  $w = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  IS  $3 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 4 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 7 \\ 4 \end{pmatrix}$ . IN FACT, EVERY VECTOR IN  $\mathbb{R}^2$  IS A L.C. OF THESE TWO.

DEF: THE SPAN OF THE VECTORS  $v_1, \dots, v_n$  IS DENOTED  $\text{SPAN} \{ v_1, \dots, v_n \}$ , AND IS THE SET OF ALL LINEAR COMBINATIONS OF  $v_1, \dots, v_n$ . I.E.

$$\text{SPAN} \{ v_1, \dots, v_n \} = \left\{ c_1 v_1 + \dots + c_n v_n \mid c_1, \dots, c_n \in \mathbb{R} \right\}$$

NOTE:  $\uparrow$  IS A VECTOR SPACE!!

THINK OF  $\text{SPAN} \{ v_1, \dots, v_n \}$  AS THE POINTS IN  $\mathbb{R}^n$  A BUG CAN GO TO IF IT CAN WALK ONLY IN THE DIRECTIONS OF  $v_1, \dots$ , AND  $v_n$ .

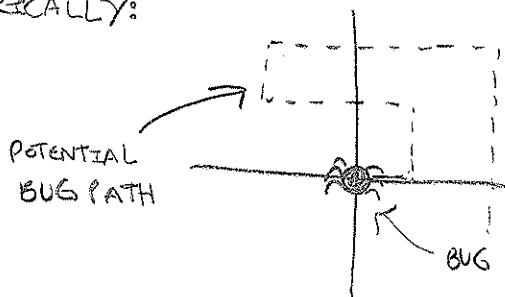
STARTING AT THE ORIGIN!!

EX'S: ①  $\text{SPAN} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} = \left\{ c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \mid c_1, c_2 \in \mathbb{R} \right\}$   
 $= \left\{ \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \right\}$

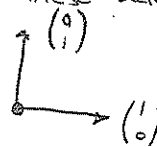
WILL DROP THIS NOTATION

THUS WE CAN GET ANY VECTOR IN  $\mathbb{R}^2$  BY CHOOSING  $c_1$  AND  $c_2$

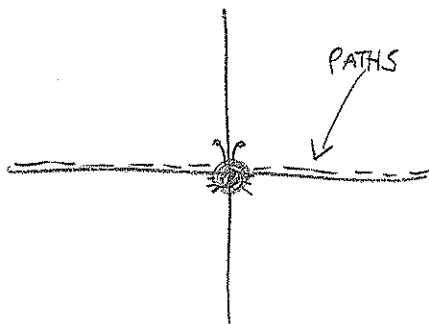
GEOMETRICALLY:



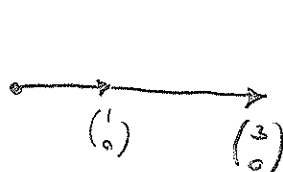
BUG CAN GO IN THESE DIRECTIONS:



②  $\text{SPAN} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right\} = \left\{ c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right\} = \left\{ \begin{pmatrix} c_1 + 3c_2 \\ 0 \end{pmatrix} \right\} = \text{JUST THE X-AXIS}$

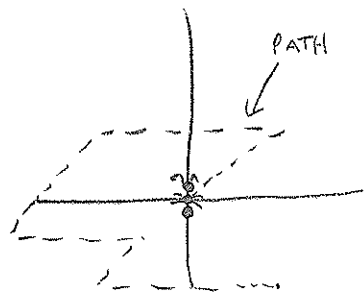


BUG CAN GO IN THESE DIRECTIONS:

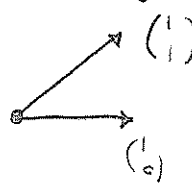


(B.C.G.I.T.D.)

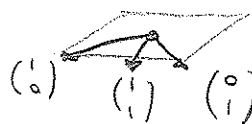
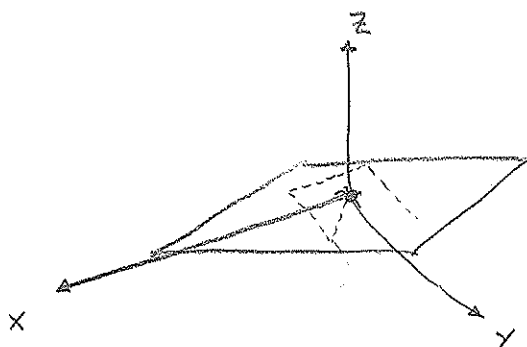
$$\textcircled{3} \text{ SPAN } \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} = \left\{ c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\} = \left\{ \begin{pmatrix} c_1 + c_2 \\ c_2 \end{pmatrix} \right\} = \mathbb{R}^2$$



B.C.G.I.T.D.



$$\textcircled{4} \text{ SPAN } \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} = \left\{ c_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} = \left\{ \begin{pmatrix} c_1 + c_2 + c_3 \\ c_2 \\ c_3 \end{pmatrix} \right\} = \text{XY-PLANE}$$



B.C.G.I.T.D.

BUG  
IS STUCK ON XY-PLANE

NOTICE THAT IN EXAMPLES  $\textcircled{2}$  AND  $\textcircled{4}$  WE COULD TOSS OUT 1 VECTOR AND STILL HAVE THE SAME SPAN.

$$\text{IN } \textcircled{2}, \text{ SPAN } \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \end{pmatrix} \right\} = \text{SPAN } \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$$

$$\text{IN } \textcircled{4}, \text{ SPAN } \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} = \text{SPAN } \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \right\}$$

THIS IS PRECISELY BECAUSE THOSE VECTORS WE DROPPED WERE LINEAR COMBINATIONS OF THE OTHER VECTORS, I.E. THEY WERE NOT "INDEPENDENT" DIRECTIONS. THIS MOTIVATES:

DEF: VECTORS  $V_1, \dots, V_n$  ARE SAID TO BE LINEARLY INDEPENDENT (L.I.) IF NO ONE OF THEM IS A LINEAR COMBINATION OF THE OTHERS. IF ONE IS A LINEAR COMBINATION OF THE OTHERS, THE VECTORS ARE SAID TO BE LINEARLY DEPENDENT (L.D.).

AN EQUIVALENT DEFINITION OF L.I. IS:

THE VECTORS  $V_1, \dots, V_n$  ARE L.I. IF THE ONLY LINEAR COMBINATION OF THEM THAT IS ZERO IS WHEN ALL THE CONSTANTS ARE ZERO. I.E.

$$c_1 V_1 + c_2 V_2 + \dots + c_n V_n = 0 \implies c_1 = 0, c_2 = 0, \dots, c_n = 0$$

(IMPLIES)

NOW A SHORT PROOF TO SHOW THAT THESE DEFINITIONS ARE EQUIVALENT:

● SUPPOSE THAT NO ONE OF THE VECTORS  $V_1, \dots, V_n$  IS A LINEAR COMBINATION IN THE OTHERS. NOW IF  $c_1 V_1 + c_2 V_2 + \dots + c_n V_n = 0$ , IF ANY OF THE  $c$ 'S ARE NONZERO WE CAN DIVIDE BY IT (SAY  $c_1 \neq 0$ ):

$$V_1 + \frac{c_2}{c_1} V_2 + \frac{c_3}{c_1} V_3 + \dots + \frac{c_n}{c_1} V_n = 0$$

AND SO  $V_1$  IS A LINEAR COMBINATION OF  $V_2, \dots, V_n$  (CONTRADICTION!)  
THUS, ALL THE  $c$ 'S = 0. SO WE HAVE ONE IMPLICATION.

● SUPPOSE  $c_1 V_1 + \dots + c_n V_n = 0 \implies c_1 = \dots = c_n = 0$

NOW IF ONE OF THE  $V$ 'S (SAY  $V_1$ ) WERE A LINEAR COMBINATION OF THE OTHERS, WE WOULD HAVE  $V_1 = c_2 V_2 + \dots + c_n V_n$

$$\text{SO } -V_1 + c_2 V_2 + \dots + c_n V_n = 0$$

BUT THIS CANNOT HAPPEN BY OUR ASSUMPTION ABOVE!

THUS, NO ONE OF THE  $V$ 'S IS A LINEAR COMBINATION OF THE OTHERS.



DEF: THE DIMENSION OF A VECTOR SPACE  $V$  IS THE LARGEST NUMBER OF L.I. VECTORS ONE CAN HAVE IN IT.

EX:  $\mathbb{R}^2$ .  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  AND  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  ARE L.I. SINCE THEY ARE NOT SCALAR MULTIPLES OF ONE ANOTHER. NOW CAN WE ADD ANOTHER VECTOR  $\begin{pmatrix} a \\ b \end{pmatrix}$  S.T.

$\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} a \\ b \end{pmatrix} \right\}$  ARE L.I.?

NO.  $\begin{pmatrix} a \\ b \end{pmatrix} = a \begin{pmatrix} 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \end{pmatrix}$  IS A LINEAR COMBINATION OF THE OTHERS.

THUS  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  ARE L.I. AND WE CANNOT ADD ANY MORE VECTORS TO GET A L.I. SET, SO  $\dim(\mathbb{R}^2) = 2$ .

EX:  $\mathbb{R}^3$ .  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$  ARE L.I. SINCE IF FOR SOME  $c_1, c_2, c_3$  WE HAVE:

$$c_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

THEN  $\begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \implies c_1 = c_2 = c_3 = 0$  (WE'RE USING THE OTHER EQUIV. DEFINITION OF L.I. HERE)

ALSO, WE CAN'T ADD ANOTHER VECTOR  $\begin{pmatrix} a \\ b \\ c \end{pmatrix} = a \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + c \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

TO GET A L.I. SET  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} a \\ b \\ c \end{pmatrix} \right\}$  SINCE  $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$  IS A L.C. OF THE OTHERS

DEF: IN  $V$  IS AN  $n$ -DIMENSIONAL VECTOR SPACE, WE CALL A SET OF VECTORS  $\{v_1, \dots, v_n\}$  A BASIS IF THEY ARE L.I.  
 $\uparrow$   
 $n$  OF THEM

SO A BASIS IS ONE OF THESE LARGEST SETS OF L.I. VECTORS.

EX: IN  $\mathbb{R}^2$ ,  $\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$  IS A BASIS

IN  $\mathbb{R}^3$ ,  $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$  IS A BASIS

IN  $\mathbb{R}^n$ ,  $\{e_1, \dots, e_n\}$  IS A BASIS

THM: IF  $v_1, \dots, v_n$  IS A BASIS FOR  $V$ , THEN ANY VECTOR  $W$  IS A LINEAR COMBINATION OF THE  $v_1, \dots, v_n$ .

PF: SINCE  $\{v_1, \dots, v_n\}$  IS A BASIS, IT IS THE LARGEST L.I. SET OF VECTORS AND THUS  $\{v_1, \dots, v_n, W\}$  ARE L.D. THIS IMPLIES THAT THERE EXISTS CONSTANTS  $c_1, \dots, c_n, c_{n+1} \in \mathbb{R}$  NOT ALL ZERO S.T.

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n + c_{n+1} W = 0$$

IF  $c_{n+1} = 0$ , WE HAVE:  $c_1 v_1 + \dots + c_n v_n = 0$

BUT THIS  $\implies c_1 = \dots = c_n = 0$  SINCE  $\{v_1, \dots, v_n\}$  ARE L.I.

SO  $c_{n+1} \neq 0$ , AND WE CAN DIVIDE BY IT:

$$\frac{c_1}{c_{n+1}} v_1 + \frac{c_2}{c_{n+1}} v_2 + \dots + \frac{c_n}{c_{n+1}} v_n + W = 0$$

MOVE OVER HERE

SO  $W$  IS A LINEAR COMB. OF  $v_1 \dots v_n$ . ■

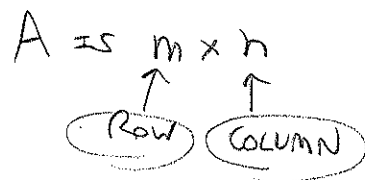
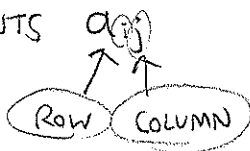
## MATRICES

AN  $m \times n$  MATRIX  $A$  IS AN ARRAY OF #'S WITH  $m$  ROWS AND  $n$  COLUMNS

WE TYPICALLY LABEL THE ELEMENTS

FOR EXAMPLE IF  $A$  IS  $2 \times 2$ :

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$



① IF  $A$  AND  $B$  ARE BOTH  $m \times n$ , WE CAN ADD THEM:

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} + \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix} = \begin{pmatrix} 1+5 & 2+6 \\ 3+7 & 4+8 \end{pmatrix} = \begin{pmatrix} 6 & 8 \\ 10 & 12 \end{pmatrix}$$

② WE CAN SCALE A MATRIX:

$$2 \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 2 & 4 \\ 6 & 8 \end{pmatrix}$$

③ IF A IS  $m \times n$  AND B IS  $n \times p$ , WE CAN MULTIPLY TO GET AN  $m \times p$  MATRIX

$$\begin{array}{c}
 \begin{array}{ccc}
 \boxed{m \times n} & \boxed{n \times p} & \\
 \uparrow & \uparrow & \\
 \boxed{m \times n} & \boxed{n \times p} & \\
 \uparrow & & \\
 \boxed{m \times p} & & 
 \end{array}
 \end{array}$$

MUST BE EQUAL IN ORDER TO MULTIPLY!

$$\text{IF } A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad B = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \quad C = \begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{pmatrix}$$

$$\text{THEN } \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{pmatrix}$$

WHERE  $C_{ij} = (\text{ITH ROW OF } A) \cdot (\text{JTH COLUMN OF } B)$   
↑  
 DOT PRODUCT

$$\text{EX: } \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} \text{1ST ROW } A \cdot \text{1ST COL } B & \text{1ST ROW } A \cdot \text{2ND COL } B \\ (1,2) \cdot (0,-1) & (1,2) \cdot (1,2) \\ (3,4) \cdot (0,-1) & (3,4) \cdot (1,2) \end{pmatrix} = \begin{pmatrix} -2 & 5 \\ -4 & 11 \end{pmatrix}$$

• IF A IS  $m \times n$  AND B IS  $r \times s$ , WITH  $n \neq r$  WE CANNOT MULTIPLY

$$\begin{array}{c}
 AB \\
 \boxed{m \times n} \neq \boxed{r \times s}
 \end{array}$$

• MATRIX MULTIPLICATION IS NOT COMMUTATIVE.

$$\text{EX: } A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \text{THEN } \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ x \end{pmatrix} \quad \text{A SWAPS } x \text{ \& } y$$

$$B = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{THEN } \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x \\ y \end{pmatrix} \quad \text{B DOUBLES } x$$

$$AB \begin{pmatrix} x \\ y \end{pmatrix} = A \begin{pmatrix} 2x \\ y \end{pmatrix} = \begin{pmatrix} y \\ 2x \end{pmatrix}$$

$$BA \begin{pmatrix} x \\ y \end{pmatrix} = B \begin{pmatrix} y \\ x \end{pmatrix} = \begin{pmatrix} 2y \\ x \end{pmatrix}$$

NOT THE SAME!

A FEW PROPERTIES OF MATRIX MULTIPLICATION / ADDITION:

- $A + B = B + A$  (CAPS ARE MATRICES)
- $(A + B) + C = A + (B + C)$
- $c_1(c_2A) = (c_1c_2)A$   $c_1, c_2 \in \mathbb{R}$
- $c(A + B) = cA + cB$   $c \in \mathbb{R}$
- $(c_1 + c_2)A = c_1A + c_2A$   $c_1, c_2 \in \mathbb{R}$
- $A(BC) = (AB)C$
- $A(B + C) = AB + AC$
- $(A + B)C = AC + BC$

WE CAN VIEW AN  $m \times n$  MATRIX AS A FUNCTION FROM  $\mathbb{R}^n$  TO  $\mathbb{R}^m$   
 SINCE FOR A VECTOR  $x \in \mathbb{R}^n$  (AN  $n \times 1$  MATRIX)

$$\begin{array}{c} A x \\ \uparrow \quad \uparrow \\ m \times n \quad n \times 1 \end{array} \text{ IS } \underline{m \times 1}. \text{ SO WE TAKE A VECTOR } x \in \mathbb{R}^n \text{ TO } Ax \in \mathbb{R}^m$$

WE WILL WANT TO THINK OF MATRICES AS FUNCTIONS A LOT!!

DEF: A MAP  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$  (NOTATION MEANS A FUNCTION TAKING VECTORS IN  $\mathbb{R}^n$  TO VECTORS IN  $\mathbb{R}^m$ )  
 IS CALLED A LINEAR MAP (OR FUNCTION)

IF IT SATISFIES:

$$\textcircled{1} f(v+w) = f(v) + f(w)$$

$$\textcircled{2} f(cv) = c f(v) \text{ FOR } c \in \mathbb{R}$$

★ FACT: EVERY LINEAR MAP FROM  $\mathbb{R}^n \rightarrow \mathbb{R}^m$  IS GIVEN BY SOME  $m \times n$  MATRIX,  
 MEANING THAT IT TAKES A VECTOR  $v$  TO  $Av$  FOR SOME MATRIX  $A$ .

LET'S SEE WHY THIS MIGHT BE TRUE FOR MAPS FROM  $\mathbb{R}^2$  TO  $\mathbb{R}^2$ .

FIRST OF ALL, MULTIPLICATION BY A MATRIX DOES DEFINE A LINEAR MAP

$$\text{SINCE: } A(v+w) = Av + Aw$$

$$A(cv) = cAv \text{ FOR } c \in \mathbb{R}$$

(FROM THE PROPERTIES OF MATRIX MULTIPLICATION)

NOW SUPPOSE  $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  IS LINEAR, AND  $f\left(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) = \begin{pmatrix} a \\ b \end{pmatrix}$ ,  $f\left(\begin{smallmatrix} 0 \\ 1 \end{smallmatrix}\right) = \begin{pmatrix} c \\ d \end{pmatrix}$

$$\text{THEN } f\left(\begin{smallmatrix} x \\ y \end{smallmatrix}\right) = f\left(x\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) + y\begin{smallmatrix} 0 \\ 1 \end{smallmatrix}\right)$$

$$= f\left(x\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) + f\left(y\begin{smallmatrix} 0 \\ 1 \end{smallmatrix}\right) \text{ BY } \textcircled{1}$$

$$= x f\left(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) + y f\left(\begin{smallmatrix} 0 \\ 1 \end{smallmatrix}\right) \text{ BY } \textcircled{2}$$

$$= x \begin{pmatrix} a \\ b \end{pmatrix} + y \begin{pmatrix} c \\ d \end{pmatrix} \text{ BY ASSUMPTION}$$

$$= \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

SO  $f$  CORRESPONDS TO THE MATRIX WITH COLUMNS  $f\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ ,  $f\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ .

IN GENERAL, FOR A LINEAR MAP  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

IT IS GIVEN BY A MATRIX WITH COLUMNS  $f\begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ ,  $f\begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}$ ,  $\dots$ ,  $f\begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$

$$f\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} | & | & & | \\ f(e_1) & f(e_2) & \dots & f(e_n) \\ | & | & & | \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

SO COLUMNS ARE WHERE  $f$  SENDS THE STANDARD BASIS VECTORS  $e_1, \dots, e_n$  (IN THAT ORDER!)

NOW SUPPOSE  $f$  &  $g$  ARE LINEAR MAPS FROM  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$  AND

$$f\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} \quad f\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix}$$

$$g\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} r \\ s \end{pmatrix} \quad g\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} t \\ u \end{pmatrix}$$

THEN  $g(f(v+w)) = g(f(v) + f(w)) = g(f(v)) + g(f(w))$  ①

$g(f(cv)) = g(cf(v)) = c g(f(v))$  ②

SO THE COMPOSITION  $g \circ f$  IS LINEAR AND CORRESPONDS TO A  $2 \times 2$  MATRIX.

BY ABOVE, THIS MATRIX HAS COLUMNS  $g \circ f\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  AND  $g \circ f\begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\begin{aligned} g \circ f\begin{pmatrix} 1 \\ 0 \end{pmatrix} &= g\begin{pmatrix} a \\ b \end{pmatrix} = g\left(a\begin{pmatrix} 1 \\ 0 \end{pmatrix} + b\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) \\ &= g\left(a\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) + g\left(b\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) \text{ BY ①} \\ &= a g\begin{pmatrix} 1 \\ 0 \end{pmatrix} + b g\begin{pmatrix} 0 \\ 1 \end{pmatrix} \text{ BY ②} \\ &= a\begin{pmatrix} r \\ s \end{pmatrix} + b\begin{pmatrix} t \\ u \end{pmatrix} \text{ BY ASSUMPTION} \\ &= \begin{pmatrix} ar + bt \\ as + bu \end{pmatrix} \text{ COLUMN 1} \end{aligned}$$

SIMILARLY,  $g \circ f\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} cr + dt \\ cs + du \end{pmatrix}$  COLUMN 2 THUS WE HAVE:

