

LAST TIME:

- WE TALKED ABOUT HOW:

$$\text{RK}(A) = \# \text{ L.I. ROWS} = \# \text{ L.I. COLUMNS}$$

IN PARTICULAR THIS GAVE US A WAY TO TELL IF n VECTORS V_1, \dots, V_n ARE L.I.:
PUT THEM AS THE ROWS OR COLUMNS OF A MATRIX AND THE RANK TELLS US HOW
MANY OF THE V 'S ARE L.I.. SO $\{V_1, \dots, V_n\}$ ARE L.I. IFF THE MATRIX IS RANK n .

- WE DEFINED THE DETERMINANT FOR $n \times n$ MATRICES AND SAW HOW IT BEHAVED UNDER ROW OPERATIONS

- WE DEFINED A^{-1} FOR AN $n \times n$ MATRIX A , AND FOUND IT TWO DIFFERENT WAYS:

$$\textcircled{1} \quad A^{-1} = \frac{1}{\det A} \text{ADJ } A$$

$$\textcircled{2} \quad (A \mid I) \xrightarrow{\text{ROW REDUCE}} (I \mid A^{-1})$$

- WE SAW A VERY IMPORTANT STRING OF EQUIVALENT STATEMENTS:

$$\textcircled{\text{C}} \quad A^{-1} \text{ EXISTS} \iff \det A \neq 0 \iff \text{RK}(A) = n$$

(WHERE A IS $n \times n$)

LAST TIME WE FOUND A^{-1} OF $A = \begin{pmatrix} 6 & 0 \\ -3 & 2 \end{pmatrix}$: $A^{-1} = \begin{pmatrix} \frac{1}{6} & 0 \\ \frac{1}{4} & \frac{1}{2} \end{pmatrix}$

THE UTILITY OF INVERSES IS THIS: SUPPOSE WE WANT TO SOLVE THE SYSTEM:

$$\begin{aligned} 6x &= 2 \\ -3x + 2y &= 1 \end{aligned} \iff \begin{pmatrix} 6 & 0 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

JUST MULTIPLY BOTH SIDES BY A^{-1} :

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \underbrace{\begin{pmatrix} \frac{1}{6} & 0 \\ \frac{1}{4} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 6 & 0 \\ -3 & 2 \end{pmatrix}}_{A^{-1}A = I} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{1}{6} & 0 \\ \frac{1}{4} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix}$$

$$\text{so } x = \frac{1}{3}, y = 1$$

IN GENERAL, WHEN SOLVING $Ax = b$ WITH SOME $n \times n$ A WHICH IS INVERTABLE, WE CAN FIND x BY JUST MULTIPLYING BY A^{-1} AS ABOVE.

$$A^{-1}Ax = A^{-1}b \quad (\text{NOTE: } x \text{ AND } b \text{ ARE VECTORS HERE})$$

$$Ix = A^{-1}b$$

$$x = A^{-1}b$$

HOMOGENEOUS SYSTEMS

RECALL THAT A HOMOGENEOUS SYSTEM OF EQ'S IS OF THE FORM $AX = 0$. SINCE $X=0$ IS ALWAYS A SOLUTION, CALLED THE TRIVIAL SOLUTION, THE SYSTEM IS ALWAYS CONSISTENT.

SUPPOSE A IS 3×3 AND WE WANT TO SOLVE $AX = 0$. WE USE AN AUGMENTED MATRIX TO FIND SOL'S:

CASE 1 $RK(A) = 3$ THEN $\left(A \mid \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right) \xrightarrow{\text{Row Ops}} \left(\begin{array}{ccc|c} 1 & a & b & 0 \\ 0 & 1 & c & 0 \\ 0 & 0 & 1 & 0 \end{array} \right)$ FOR SOME $a, b, c \in \mathbb{R}$

THEN: $E_3: z = 0$

$E_2: y + cz = y = 0$

$E_1: x + ay + bz = x = 0$

SO $RK(A) = 3 \implies AX = 0$ HAS ONLY TRIVIAL SOLUTION

CASE 2 $RK(A) < 3$ THEN $\left(A \mid \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right) \xrightarrow{\text{Row Ops}} \left(\begin{array}{ccc|c} 1 & a & b & 0 \\ 0 & 1 & c & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$ OR $\left(\begin{array}{ccc|c} 1 & a & b & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$ OR ... (ZERO ROW SOMEWHERE)

IN ANY OF THESE CASES, WE HAVE A PARAMETER:

$\# \text{PARAMS} = \# \text{VARS} - RK(A) = 3 - RK(A) > 0$

THUS ONE OF x, y OR z WILL BE A FREE VARIABLE WE CAN CHOOSE TO BE NONZERO.

SO, $RK(A) < 3 \implies AX = 0$ HAS NONTRIVIAL SOLUTIONS

FOR AN $n \times n$ MATRIX WE HAVE (BY THE SAME REASONING)

$AX = 0$ HAS NONTRIVIAL SOLUTIONS $\iff RK(A) < n$

THE IDEA IS THAT AS LONG AS WE HAVE A PARAMETER, WE CAN CHOOSE A NONTRIVIAL SOLUTION. BUT $\# \text{PARAMS} = n - RK(A)$

SO WE HAVE PARAMETERS IFF $RK(A) < n$.

• NOW SINCE $RK(A)$ CAN ONLY BE $1, 2, 3, \dots, n-1$, OR n , $RK(A) < n$ IS EQUIVALENT

TO $RK(A) \neq n$. BUT BY (\ddot{U}) $RK(A) \neq n \iff \boxed{\text{DET}(A) = 0} \iff \bar{A}^{-1}$ DOES NOT EXIST

(WE JUST NEGATED ALL THE STATEMENTS IN (\ddot{U}))

\uparrow
ONE WE WANT

IN OTHER WORDS:

$AX = 0$ HAS NONTRIVIAL SOLUTIONS $\iff \text{DET}(A) = 0$

THIS IS WHAT WE'LL NEED TO FIND EIGENVECTORS/VALUES

EIGENVECTORS

DEF: LET A BE AN $n \times n$ MATRIX. WE SAY THAT A VECTOR $v \in \mathbb{R}^n$ IS AN EIGENVECTOR WITH EIGENVALUE $\lambda \in \mathbb{R}$ IF:

① $v \neq 0$ (NOT ZERO VECTOR)

② $Av = \lambda v$

IF WE DIDN'T RULE OUT THIS CASE, THE ZERO VECTOR WOULD BE AN EIGENVECTOR OF ANY MATRIX WITH EIGENVALUE 0

SO EIGENVECTORS OF SOME MATRIX ARE VECTORS THAT JUST SCALE BY λ WHEN MULTIPLIED BY A .

EX: $A = \begin{pmatrix} -1 & 3 \\ 0 & 2 \end{pmatrix}$ THEN $v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ IS AN EIGENVECTOR WITH WHAT EIGENVALUE?

$$Av = \begin{pmatrix} -1 & 3 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 2v$$

so $\lambda = 2$

HOW DO WE FIND THESE VECTORS? WELL, FIRST WE FIND THE λ 's.

SO, WE DESIRE A $\lambda \in \mathbb{R}$ SUCH THAT:

$\{\lambda \text{ SUCH THAT: } Av = \lambda v \text{ FOR SOME } v \neq 0\}$

$= \{\lambda \text{ SUCH THAT: } Av = \lambda I v \text{ FOR SOME } v \neq 0\}$ (I IS $n \times n$ IDENTITY MATRIX)

$= \{\lambda \text{ SUCH THAT: } (A - \lambda I)v = 0 \text{ FOR SOME } v \neq 0\}$ (FACTOR OUT v)

$= \{\lambda \text{ SUCH THAT: THE HOMOG. SYSTEM } (A - \lambda I)v = 0 \text{ HAS NONTRIVIAL SOL'S}\}$

$= \{\lambda \text{ SUCH THAT: } \det(A - \lambda I) = 0\}$ BY WHAT WE SAID BEFORE.

EX: FIND THE EIGENVALUES OF $A = \begin{pmatrix} 2 & 1 \\ 2 & 1 \end{pmatrix}$

$$\det(A - \lambda I) = \begin{vmatrix} 2 - \lambda & 1 \\ 2 & 1 - \lambda \end{vmatrix} = (2 - \lambda)(1 - \lambda) - 2$$

$$= \lambda^2 - 3\lambda + 2 - 2$$

$$= \lambda(\lambda - 3) = 0$$

$\lambda = 0$ & $\lambda = 3$

NOW ONCE WE HAVE THE λ 'S, WE CAN FIND THE EIGENVECTORS CORRESPONDING TO THEM:

$$Av = \lambda v \iff (A - \lambda I)v = 0$$

↑
SOLVE THIS SYSTEM OF EQ'S FOR EACH λ

SO CONTINUING WITH OUR ABOVE EXAMPLE:

$\lambda_1 = 0$: solve $(A - 0I)v = 0$

$$\left(\begin{array}{cc|c} 2 & 1 & 0 \\ 2 & 1 & 0 \end{array} \right) \xrightarrow{R_2 \rightarrow R_2 - R_1} \left(\begin{array}{cc|c} 2 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$2x + y = 0$$

$$x = -\frac{1}{2}y$$

$$\begin{pmatrix} -\frac{1}{2}y \\ y \end{pmatrix}$$

ARE ALL EIGENVECTORS

CHOOSE SAY $y = 2$:

$$v_1 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

λ_2 : $(A - 3I)v = 0$

$$\left(\begin{array}{cc|c} 2-3 & 1 & 0 \\ 2 & 1-3 & 0 \end{array} \right) = \left(\begin{array}{cc|c} -1 & 1 & 0 \\ 2 & -2 & 0 \end{array} \right) \xrightarrow{R_2 \rightarrow R_2 + 2R_1} \left(\begin{array}{cc|c} -1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

$$-x + y = 0$$

$$x = y$$

$$\begin{pmatrix} y \\ y \end{pmatrix}$$

ARE ALL EIGENVECTORS

CHOOSE $y = 1$:

$$v_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

NOTICE:

- OUR CHOICE OF EIGENVECTORS IS HARDLY UNIQUE - SCALING AN EIGENVECTOR STILL GIVES YOU AN EIGENVECTOR
- OUR SYSTEMS $(A - \lambda I)v = 0$ BOTH HAD PARAMETERS. IF THIS DOES NOT HAPPEN, THEN YOU EITHER ROW-REDUCED INCORRECTLY OR FOUND THE WRONG λ 'S.

EX: FIND THE EIGENVALUES/VECTORS OF $A = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$

FIND λ 'S: $\det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{vmatrix} = (2-\lambda)^2 = 0 \quad \lambda = 2, 2$

FIND v 'S: $\lambda = 2$: $(A - \lambda I)v = 0$

$$\left(\begin{array}{cc|c} 2-2 & 0 & 0 \\ 0 & 2-2 & 0 \end{array} \right) = \left(\begin{array}{cc|c} 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right)$$

NO RESTRICTIONS ON x AND y

SO ANY VECTOR $\begin{pmatrix} x \\ y \end{pmatrix}$ IS AN EIGENVECTOR

OF A . NOTICE $A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x \\ 2y \end{pmatrix} = 2 \begin{pmatrix} x \\ y \end{pmatrix}$

IN PARTICULAR NOTE THAT WE CAN CHOOSE 2 L.I. EIGENVECTORS CORRESPONDING TO $\lambda=2$, SAY $v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$. DOES THIS HAVE SOMETHING TO DO WITH $\lambda=2$ OCCURRING TWICE (MULTIPLICITY TWO)? YES

THM: SUPPOSE λ_1 IS AN EIGENVALUE OF A ($n \times n$) WITH MULTIPLICITY m (I.E. THE FACTOR $(\lambda - \lambda_1)$ OCCURS m TIMES IN $\det(A - \lambda I) = 0$). THEN THE # OF L.I. EIGENVECTORS WITH EIGENVALUE λ_1 IS AT MOST m (BUT NOT ALWAYS EQUAL TO m)

EX: FIND ALL OF THE EIGENVALUES/VECTORS OF $A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$

FIND λ 's: $\det(A - \lambda I) = \det \begin{pmatrix} 2-\lambda & 1 \\ 0 & 2-\lambda \end{pmatrix} = (2-\lambda)^2 = 0 \quad \lambda = 2, 2$

FIND v 's: $(A - 2I)v = 0 \rightarrow \left(\begin{array}{cc|c} 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right)$ so $y=0$

OUR SOLUTIONS ARE $\begin{pmatrix} x \\ 0 \end{pmatrix}$ (ONLY 1 PARAMETER)

SO WE ONLY HAVE ONE L.I. EIGENVECTOR SAY $v = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

NOTE: WHEN SOLVING $(A - \lambda I)v = 0$, # PARAMS = # OF L.I. EIGENVECTORS

RECALL THAT WE CHOSE THE λ 's SO THAT WE WOULD ALWAYS HAVE PARAMETERS.

THUS:

• TO ANY EIGENVALUE λ , THERE IS AT LEAST ONE EIGENVECTOR

EX: FIND THE EIGENVALUES/VECTORS OF $A = \begin{pmatrix} 1 & 1 & 0 \\ -4 & -3 & 0 \\ 11 & 16 & 2 \end{pmatrix}$

FIND λ 's: $\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 1 & 0 \\ -4 & -3-\lambda & 0 \\ 11 & 16 & 2-\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} 1-\lambda & 1 \\ -4 & -3-\lambda \end{vmatrix}$

$= (2-\lambda)(\lambda^2 + 2\lambda + 1)$

$\lambda_1 = 2:$

$= (2-\lambda)(\lambda+1)^2 = 0$

FIND v 's: $(A - 2I)v = 0$

$\lambda = 2, -1, -1$

$\left(\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ -4 & -5 & 0 & 0 \\ 11 & 16 & 0 & 0 \end{array} \right) \xrightarrow{\substack{R_2 \rightarrow R_2 - 4R_1 \\ R_3 \rightarrow R_3 + 11R_1}}$

$\left(\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 0 & -9 & 0 & 0 \\ 0 & 27 & 0 & 0 \end{array} \right) \xrightarrow{R_3 \rightarrow R_3 + 3R_2} \left(\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 0 & -9 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$

$$\begin{array}{l}
 R_1 \rightarrow -R_1 \\
 R_2 \rightarrow -\frac{1}{9}R_2
 \end{array}
 \left(\begin{array}{ccc|c}
 1 & -1 & 0 & 0 \\
 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 0
 \end{array} \right)
 \begin{array}{l}
 E_2: Y = 0 \\
 E_1: X - Y = X = 0 \\
 1 \text{ PARAMETER} = 1 \text{ E. VECTOR}
 \end{array}
 \text{ CHOOSE } \mathbf{v}_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda_2 = -1:$$

$$(A + I)\mathbf{v} = 0 \rightarrow \left(\begin{array}{ccc|c}
 2 & 1 & 0 & 0 \\
 -4 & -2 & 0 & 0 \\
 11 & 16 & 3 & 0
 \end{array} \right)
 \xrightarrow{\substack{R_2 \rightarrow R_2 + 2R_1 \\ R_3 \rightarrow R_3 - \frac{11}{2}R_1}}
 \left(\begin{array}{ccc|c}
 2 & 1 & 0 & 0 \\
 0 & 0 & 0 & 0 \\
 0 & \frac{21}{2} & 3 & 0
 \end{array} \right)
 \xrightarrow{\substack{R_1 \rightarrow \frac{1}{2}R_1 \\ R_3 + \frac{2}{21}R_3}}
 \left(\begin{array}{ccc|c}
 1 & \frac{1}{2} & 0 & 0 \\
 0 & 0 & 0 & 0 \\
 0 & 1 & \frac{2}{7} & 0
 \end{array} \right)$$

$$\begin{array}{l}
 R_2 \leftrightarrow R_3 \\
 \rightarrow
 \end{array}
 \left(\begin{array}{ccc|c}
 1 & \frac{1}{2} & 0 & 0 \\
 0 & 1 & \frac{2}{7} & 0 \\
 0 & 0 & 0 & 0
 \end{array} \right)
 \begin{array}{l}
 E_2: Y + \frac{2}{7}Z = 0 \\
 Y = -\frac{2}{7}Z \\
 E_1: X + \frac{1}{2}Y = 0
 \end{array}$$

1 PARAM
= 1 E. VECTOR

$$X = -\frac{1}{2}Y = -\frac{1}{2}\left(-\frac{2}{7}Z\right) = \frac{1}{7}Z$$

$$\text{SOL: } \begin{pmatrix} \frac{1}{7}Z \\ -\frac{2}{7}Z \\ Z \end{pmatrix} \text{ SO LET } Z=7: \mathbf{v}_2 = \begin{pmatrix} 1 \\ -2 \\ 7 \end{pmatrix}$$

AGAIN WE ONLY HAD 1 EVECTOR CORRESPONDING TO $\lambda = -1$ (MULTIPLICITY 2)

• COMPLEX λ 's:

THE EIGENVALUES CAN BE COMPLEX NUMBERS. IN THIS CASE, IF A IS A REAL $n \times n$ MATRIX, EIGENVALUES/VECTORS COME IN CONJUGATE PAIRS.

DEF: FOR A NUMBER $a + ib \in \mathbb{C}$ (COMPLEX #'S), THE COMPLEX CONJUGATE, DENOTED $\overline{a + ib}$, IS JUST $\overline{a + ib} = a - ib$.

• FOR ANY COMPLEX NUMBERS $z_1 = a + ib$ AND $z_2 = c + id$, $\overline{z_1 z_2} = \overline{z_1} \overline{z_2}$
SO THE "BAR" DISTRIBUTES OVER $+$ & $-$. AND $\overline{z_1 + z_2} = \overline{z_1} + \overline{z_2}$

• FOR A MATRIX A , $\overline{\overline{A}} = A$ CONJUGATED AT EACH ELEMENT:

$$\text{EX: } \overline{\begin{pmatrix} i & 3 \\ 1-i & 4 \end{pmatrix}} = \begin{pmatrix} -i & 3 \\ 1+i & 4 \end{pmatrix}$$

NOW SUPPOSE WE HAVE A $n \times n$ WITH EIGENVALUE/VECTOR λ AND V .

THEN: $AV = \lambda V$ ^(REAL)

TAKE CONJUGATE: $\overline{AV} = \overline{\lambda V}$

$\overline{A\overline{V}} = \overline{\lambda\overline{V}}$
 $A\overline{V} = \overline{\lambda}\overline{V}$ } IS BECAUSE A IS A REAL MATRIX
 SO THERE ARE NO i 'S TO FLIP

IN OTHER WORDS, IF V IS A COMPLEX EIGENVECTOR OF A REAL MATRIX A WITH COMPLEX EIGENVALUE λ , THEN \overline{V} IS ANOTHER EIGENVECTOR OF A WITH EIGENVALUE $\overline{\lambda}$.

EX: FIND EIGENVALUES/VECTORS OF $A = \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix}$

FIND λ 's: $\det(A - \lambda I) = \begin{vmatrix} 2-\lambda & -1 \\ 1 & 2-\lambda \end{vmatrix} = (2-\lambda)^2 + 1 = 0$
 $(2-\lambda)^2 = -1$... TAKE $\sqrt{\quad}$

$2-\lambda = \pm i$

$2 \pm i = \lambda$

SO $\lambda_1 = 2+i$ $\lambda_2 = 2-i$
 $\lambda_1 = \overline{\lambda_2}$

FIND V 's: $(A - (2+i)I)V = 0$

$\lambda_1 = 2+i$:

$\left(\begin{array}{cc|c} -i & -1 & 0 \\ 1 & -i & 0 \end{array} \right) \xrightarrow{R_1 \rightarrow R_1 + iR_2} \left(\begin{array}{cc|c} 0 & 0 & 0 \\ 1 & -i & 0 \end{array} \right)$ $x - iy = 0$
 $x = iy$
 1 PARAM

$\begin{pmatrix} iy \\ y \end{pmatrix}$ ARE ALL E. VECTORS
 CHOOSE $y=1$

$V_1 = \begin{pmatrix} i \\ 1 \end{pmatrix}$

BY ABOVE, WE KNOW WE CAN LET

$V_2 = \begin{pmatrix} -i \\ 1 \end{pmatrix} = \overline{V_1}$ BE AN EIGENVECTOR FOR λ_2

BUT LET'S JUST CHECK THAT:

$\lambda_2 = 2-i$: $(A - (2-i)I)V = 0$

$\left(\begin{array}{cc|c} i & -1 & 0 \\ 1 & i & 0 \end{array} \right) \xrightarrow{R_1 \rightarrow R_1 - iR_2} \left(\begin{array}{cc|c} 0 & 0 & 0 \\ 1 & i & 0 \end{array} \right)$ $x + iy = 0$
 $x = -iy$
 $\begin{pmatrix} -iy \\ y \end{pmatrix}$ ALL E. VECTORS
 CHOOSE $y=1$

$V_2 = \begin{pmatrix} -i \\ 1 \end{pmatrix}$

RMK: SINCE $\det(A)$ FOR AN UPPER OR LOWER TRIANGULAR MATRIX IS THE PRODUCT ALONG THE DIAGONAL, WE HAVE: THAT FOR ANY UPPER OR LOWER TRIANGULAR MATRIX, THE EIGENVALUES ARE THE DIAGONAL ELEMENTS.

EX: $A = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 3 & 0 & 0 \\ 1 & 0 & 4 & 0 \\ 0 & 0 & 2 & -1 \end{pmatrix}$ $\det(A - \lambda I) = \begin{vmatrix} -\lambda & 0 & 0 & 0 \\ 1 & 3-\lambda & 0 & 0 \\ 1 & 0 & 4-\lambda & 0 \\ 0 & 0 & 2 & -1-\lambda \end{vmatrix} = -\lambda(3-\lambda)(4-\lambda)(-1-\lambda)$
 so $\lambda = 0, 3, 4, -1$

DIAGONALIZATION

DEF: AN $n \times n$ MATRIX A IS SAID TO BE DIAGONALIZABLE IF THERE EXISTS SOME MATRIX P THAT IS INVERTABLE AND A DIAGONAL MATRIX D s.t.

$$PD = AP$$

"PRETTY DOGS = AWESOME PETS"

HOW DO WE KNOW WHEN WE CAN DO THIS? HERE IS WHEN:

★ THM: AN $n \times n$ MATRIX A IS DIAGONALIZABLE IFF IT HAS n L.I. EIGENVECTORS. THEN, SUPPOSE A HAS EIGENVECTORS v_1, \dots, v_n AND VALUES $\lambda_1, \dots, \lambda_n$, THEN:

$$P = \text{MATRIX WITH COLUMNS } \left(v_1 \mid v_2 \mid \dots \mid v_n \right)$$

$$D = \text{DIAGONAL WITH ELEMENTS } \lambda_1 \dots \lambda_n = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{pmatrix}$$

ONE THING THAT IS TRUE:

THM: FOR ANY $n \times n$ MATRIX A , THE EIGENVECTORS CORRESPONDING TO DIFFERENT λ 'S ARE ALL L.I.

PF: SUPPOSE $v_1 \sim \lambda_1, v_2 \sim \lambda_2, \dots, v_k \sim \lambda_k$ ARE ALL EIGENVECTORS/VALUES OF A , WITH ALL λ 'S BEING DISTINCT. WE SUPPOSE $c_1 v_1 + \dots + c_k v_k = 0$.

WE WANT TO SHOW THAT ALL THE c 'S = 0

WE PROVE BY INDUCTION ON k .

IF $k=2$:

$$\star c_1 v_1 + c_2 v_2 = 0 \quad \lambda_1 \neq \lambda_2$$

$$\text{SO } c_1 A v_1 + c_2 A v_2 = 0 \quad (\text{MULT } \star \text{ BY } A) \quad \text{AND} \quad c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 = 0 \quad (\text{MULT } \star \text{ BY } \lambda_1)$$

$$= c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 = 0$$

SUBTRACTING THESE TWO EQ'S \swarrow

$$c_2 (\lambda_1 - \lambda_2) v_2 = 0$$

$$\text{SO } c_2 = 0 \text{ OR } \underbrace{\lambda_1 = \lambda_2}_{\text{NOT TRUE}} \quad (v_2 \text{ IS NOT A ZERO VECTOR BY DEF. OF AN E. VECTOR})$$

SO $c_2 \neq 0$. THUS $c_1 = 0$ AS WELL, AND WE HAVE PROVEN THE CASE $k=2$.

NOW FOR THE GENERAL CASE:

$$\hookrightarrow c_1 v_1 + c_2 v_2 + \dots + c_k v_k = 0 \quad \lambda_i \text{ 'S DISTINCT}$$

$$\text{SO } c_1 A v_1 + c_2 A v_2 + \dots + c_k A v_k = 0 \quad \text{AND} \quad c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 + \dots + c_k \lambda_k v_k = 0$$

$$c_1 \lambda_1 v_1 + c_2 \lambda_2 v_2 + \dots + c_k \lambda_k v_k = 0$$

(MULT EQ 2 BY λ_1)

SUBTRACTING THESE TWO EQ'S: ($c_1 \lambda_1 v_1$ CANCELS)

$$c_2 (\lambda_1 - \lambda_2) v_2 + c_3 (\lambda_1 - \lambda_3) v_3 + \dots + c_k (\lambda_1 - \lambda_k) v_k = 0$$

BUT BY INDUCTION, THE $k-1$ EIGENVECTORS $v_2 \dots v_k$ ARE L.I., THUS

$$c_2 (\lambda_1 - \lambda_2) = 0, \quad c_3 (\lambda_1 - \lambda_3) = 0, \quad \dots \quad c_k (\lambda_1 - \lambda_k) = 0$$

BUT THEN BY DISTINCTNESS OF THE λ_i 'S, $c_2 = c_3 = \dots = c_k = 0$, AND

THUS SO ALSO DOES c_1 . THIS PROVES THE GENERAL CASE \blacksquare

BY THIS THM, FIND OUT IF WE CAN DIAGONALIZE A CAN BE REDUCED TO CHECKING L.I. OF EIGENVECTORS FOR EACH λ SEPARATELY, NAMELY:

① TO SEE IF YOU CAN DIAGONALIZE A YOU \star

① FIND ALL OF THE EIGENVALUES

② FOR EACH λ OF MULTIPLICITY m , SEE IF YOU CAN FIND m L.I. EIGENVECTORS CORRESPONDING TO λ .

③ IF YOU CAN FIND SUCH VECTORS IN ② FOR ALL λ 'S, A IS DIAGONALIZABLE. IF NOT, A IS NOT DIAGONALIZABLE.

THIS IS ABOUT ALL YOU WILL NEED TO KNOW

EX: CAN WE DIAGONALIZE $A = \begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix}$?

FIND λ 's: $\det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 1 \\ 0 & 3-\lambda \end{vmatrix} = (2-\lambda)(3-\lambda) \quad \lambda=2,3$

TO EACH λ , WE HAVE AT LEAST ONE E. VECTOR. THE V 'S FOR $\lambda=2$ AND $\lambda=3$ WILL BE L.I. BY OUR THM, SO YES WE CAN DIAGONALIZE. LET'S CHECK:

FIND V 's:

$\lambda_1=2$: $(A - 2I)V = 0$

$\begin{pmatrix} 0 & -1 & | & 0 \\ 0 & 1 & | & 0 \end{pmatrix} \rightarrow y=0$ so $V_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$\lambda_2=3$: $(A - 3I)V = 0$

$\begin{pmatrix} -1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{pmatrix} \rightarrow x=y$ so $V_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

SO BY OUR THM WE CAN LET $P = (V_1 | V_2) = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ AND $D = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$

THEN $PD = AP$

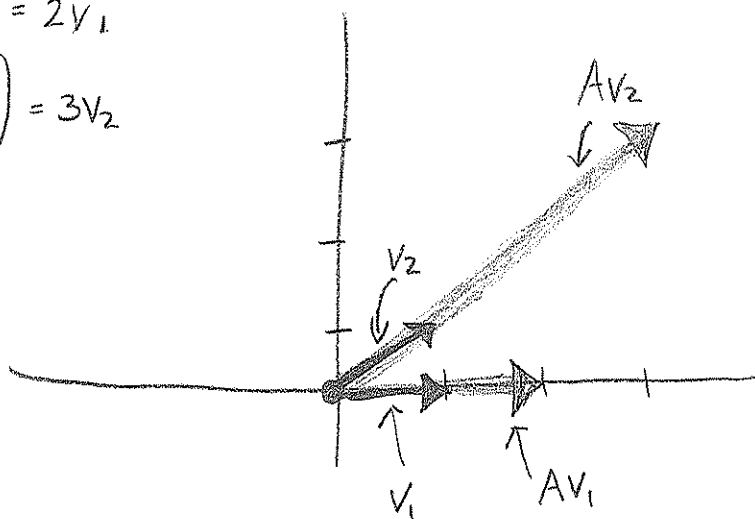
$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$

$\begin{pmatrix} 2 & 3 \\ 0 & 3 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 0 & 3 \end{pmatrix} \checkmark$

GEOMETRICALLY, WHAT IS GOING ON? A IS JUST SCALING THESE TWO VECTORS.

$AV_1 = A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2V_1$

$AV_2 = A \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 3V_2$



SINCE v_1 AND v_2 ARE L.I., EVERY VECTOR IN \mathbb{R}^2 IS A LINEAR COMBINATION OF THEM. SINCE A ACTS VERY SIMPLY ON THESE VECTORS, WE CAN ESSENTIALLY CHANGE MATRIX MULTIPLICATION TO SCALING BY THE λ 'S.

$$\text{EX: } A = \begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix}$$

$$\begin{aligned} \text{THEN } A \begin{pmatrix} 4 \\ 2 \end{pmatrix} &= A \left(2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right) \\ &= 2 A \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 2 A \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= 2 (3) \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 2 (2) \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{USING } Av = \lambda v \\ &= \begin{pmatrix} 6 \\ 6 \end{pmatrix} + \begin{pmatrix} 4 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} 10 \\ 6 \end{pmatrix} \end{aligned}$$

WE CAN REWRITE $PD = AP$ AS $PD\bar{P}^{-1} = A$

NOTICE THAT IN OUR EXAMPLE $P \begin{pmatrix} 1 \\ 0 \end{pmatrix} = v_1$, $P \begin{pmatrix} 0 \\ 1 \end{pmatrix} = v_2$

SO $\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \bar{P}^{-1} v_1$, $\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \bar{P}^{-1} v_2$

SO IF WE THINK OF MULTIPLICATION BY A IS MULT. BY $PD\bar{P}^{-1}$,

$$Av_1 = PD\bar{P}^{-1}v_1 = PD \begin{pmatrix} 1 \\ 0 \end{pmatrix} = P \cdot 2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2P \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2v_1$$

IN OTHER WORDS, \bar{P}^{-1} TAKES THE EIGENVECTORS TO THE STANDARD BASIS VECTORS

• D SCALES THEM ACCORDING TO THE CORRECT λ

• P PUTS EVERYTHING BACK IN TERMS OF THE EIGENVECTORS

FOR THIS REASON, WE CALL P THE "CHANGE OF BASIS" MATRIX CORRESPONDING TO CHANGING BETWEEN THE STANDARD BASIS AND THE BASIS OF EIGENVECTORS. THE POINT IS THAT IF YOU CHOOSE THE BASIS OF EIGENVECTORS AND PUT ALL OF THE VECTORS IN TERMS OF THEM (AS ABOVE) MULT. BY A IS VERY SIMILAR TO MULT. BY D .

EX: $A = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$ CAN YOU DIAGONALIZE A?

$$\begin{aligned} \lambda\text{'s: } \det(A - \lambda I) &= \begin{vmatrix} 2-\lambda & 0 & 0 & 0 \\ 0 & 2-\lambda & 0 & 0 \\ 0 & 0 & -\lambda & 1 \\ 0 & 0 & 1 & -\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} 2-\lambda & 0 & 0 \\ 0 & -\lambda & 1 \\ 0 & 1 & -\lambda \end{vmatrix} \\ &= (2-\lambda)^2 \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} \\ &= (2-\lambda)^2 (\lambda^2 - 1) = 0 \end{aligned}$$

LET $\lambda_1 = 1, \lambda_2 = -1, \lambda_3 = 2$ (MULT 2)

FOR λ_1 & λ_2 WE WILL HAVE EXACTLY ONE L.I. E-VECTOR. THIS IS BECAUSE THERE IS ALWAYS AT LEAST ONE, AND AT MOST m WHERE m IS THE MULTIPLICITY OF THE λ (WHICH IS 1). λ_3 COULD HAVE 1 OR 2 L.I. E-VECTORS. IF IT IS 2, WE CAN DIAGONALIZE. SO WE CHECK:

FOR λ_3 :

$(A - 2I)V = 0$ CORRESPONDS TO:

$$\left(\begin{array}{cccc|c} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 0 \end{array} \right) \xrightarrow{R_3 \rightarrow R_3 + 2R_4} \left(\begin{array}{cccc|c} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -3 & 0 \\ 0 & 0 & 1 & -2 & 0 \end{array} \right)$$

SINCE WE HAVE 4 VARIABLES WE USE x, y, z & w .
 $E_3: -3w = 0$ SO $w = 0$
 $E_4: -2z = -2z = 0$ SO $z = 0$

OUR EIGENVECTORS FOR $\lambda = 2$ ARE:

$\begin{pmatrix} x \\ y \\ 0 \\ 0 \end{pmatrix}$ FOR ANY x, y SO CHOOSE

$V_3 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad V_4 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ BOTH L.I.

THUS WE CAN DIAGONALIZE

LET'S FIND P & D TO COMPLETE THE EXAMPLE

WE NEED THE EIGENVECTORS TO λ_1 & λ_2 :

$$\lambda_1: (A - 0I)v = 0 \quad \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{array} \right) \xrightarrow{R_4 + R_3} \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$E_1: x=0$$

$$E_2: y=0$$

$$E_3: -z+w=0 \text{ so } z=w$$

$$\begin{pmatrix} 0 \\ 0 \\ z \\ z \end{pmatrix} \text{ ALL E. VECTORS CHOOSE } z=1$$

$$v_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

$$\lambda_2: (A - (-1)I)v$$

$$\left(\begin{array}{cccc|c} 3 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \end{array} \right) \xrightarrow{\begin{array}{l} R_4 \rightarrow R_4 - R_3 \\ R_1 \rightarrow \frac{1}{3}R_1 \\ R_2 \rightarrow \frac{1}{3}R_2 \end{array}}$$

$$\left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$E_1: x=0$$

$$E_2: y=0$$

$$E_3: z+w=0 \text{ so } z=-w$$

$$\begin{pmatrix} 0 \\ 0 \\ z \\ -z \end{pmatrix} \text{ ARE ALL E. VECTORS CHOOSE } z=1$$

$$v_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix}$$

$$P = \left(\begin{array}{c|c|c|c} v_1 & v_2 & v_3 & v_4 \end{array} \right) = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \end{pmatrix}$$

$$\text{AND } D = \begin{pmatrix} \lambda_1 & 0 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 \\ 0 & 0 & \lambda_3 & 0 \\ 0 & 0 & 0 & \lambda_3 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

THE ORDER IS VERY IMPORTANT. NOTICE HOW THE 1ST COLUMN OF P (WHICH IS v_1) HAS E. VALUE λ_1 (1ST COLUMN OF D) AND THE 2ND COLUMN OF P (WHICH IS v_2) HAS E. VALUE λ_2 (2ND COLUMN OF D) ETC.

CHECK THAT

$$PD = AP$$