

PRACTICE QUESTIONS FOR MIDTERM 1

1. Let

$$A = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 1 & 1 & 2 & 1 \\ 2 & 3 & 2 & 2 \\ 0 & 1 & -2 & 0 \end{pmatrix}$$

- Find the rank of A
- Find the dimensions of and bases for $\text{rowsp}(A)$, $\text{colsp}(A)$, $\text{nullsp}(A)$
- Determine whether the vector $(1, 0, -2, 3) \in \text{rowsp}(A)$
- Extend the basis for $\text{colsp}(A)$ to a basis for \mathbb{R}^4 .

Solution: (a & b) Row-reducing, we get

$$R = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

A therefore has rank 2. A basis for the row space is given by the first two rows of R . The pivot variables are x_1, x_2 , which means that the first two columns of A form a basis for the column space. To get the nullspace, we solve the system

$$x_1 + 2x_2 + x_4 = 0$$

$$-x_2 + 2x_3 = 0$$

in terms of the non-pivot variables x_3, x_4 . We get $x_2 = 2x_3$, $x_1 = -4x_3 - x_4$. The nullspace therefore has the form

$$(-4x_3 - x_4, 2x_3, x_3, x_4) = x_3(-4, 2, 1, 0) + x_4(-1, 0, 0, 1)$$

so $(-4, 2, 1, 0), (-1, 0, 0, 1)$ form a basis.

(c) Suppose $(1, 0, -2, 3) \in \text{rowsp}(A)$ - then there are constants a, b such that

$$(1, 0, -2, 3) = a(1, 2, 0, 1) + b(0, -1, 2, 0)$$

This forces $a = 1, b = 2$, but the third equation yields $2b = -2$, which means the system is inconsistent. Thus $(1, 0, -2, 3)$ is not in the $\text{rowsp}(A)$.

(d) We want to extend $(1, 1, 2, 0), (2, 1, 3, 1)$ to a basis for \mathbb{R}^4 . Putting these as rows in a 2×4 matrix and row-reducing, we get

$$\begin{pmatrix} 1 & 1 & 2 & 0 \\ 0 & -1 & -1 & 1 \end{pmatrix}$$

It follows that adding $(0, 0, 1, 0), (0, 0, 0, 1)$ yields a basis for \mathbb{R}^4 .

2. Determine whether

$$B = \begin{pmatrix} 1 & 2 & 0 \\ 1 & 1 & 2 \\ 2 & 3 & 1 \end{pmatrix}$$

is non-singular. If so, find B^{-1} .

Solution: Row - reducing, we get

$$R = \begin{pmatrix} 1 & 2 & 0 \\ 0 & -1 & 2 \\ 0 & 0 & -1 \end{pmatrix}$$

All three pivots are non-zero, so the matrix is non-singular.

3. Find a basis for the smallest subspace of \mathbb{R}^6 containing the two subspaces $W_1 = \text{span}\{(1, 2, 3, 0, 3, 2), (0, 0, 1, 2, 1, 0)\}$ and $W_2 = \text{span}\{(1, 2, 2, -2, 2, 2), (0, 0, 1, 2, 1, 1)\}$.

Solution: The smallest subspace is spanned by the four vectors $(1, 2, 3, 0, 3, 2), (0, 0, 1, 2, 1, 0), (1, 2, 2, -2, 2, 2), (0, 0, 1, 2, 1, 1)$. To find a basis, put these as rows of a 4×6 matrix A and row-reduce.

$$A = \begin{pmatrix} 1 & 2 & 3 & 0 & 3 & 2 \\ 1 & 2 & 2 & -2 & 2 & 2 \\ 0 & 0 & 1 & 2 & 1 & 0 \\ 0 & 0 & 1 & 2 & 1 & 1 \end{pmatrix}$$

$$R = \begin{pmatrix} 1 & 2 & 3 & 0 & 3 & 2 \\ 0 & 0 & -1 & -2 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

We exchange rows 3 and 4 to get the zero row at the bottom. A basis for the desired subspace is therefore given by the three non-zero rows of R .

4.) Determine whether the statements are true or false. If true, say why, if false, give a counterexample.

- (1) Let A be a 3×5 matrix such that $(1, 1, 1, 1, 1)$, $(0, 1, 1, 1, 1)$, $(0, 0, 1, 1, 1)$ are in $\text{nullsp}(A)$. The rows of A are linearly independent.
Solution: F $\text{null}(A) \geq 3$, so by the rank-nullity theorem, $\text{rk}(A) \leq 2$. The three rows are therefore linearly dependent.
- (2) With A as in 1, the equation $Ax = B$ has a solution for every $B \in \mathbb{R}^3$.
Solution: F $\text{rk}(A) \leq 2$, and we would need rank 3 to guarantee a solution for every B .
- (3) For A as in 1, the solution to $Ax = B$ when it exists is unique.
Solution: F When $B = 0$, we are dealing with the nullspace, which is at least three-dimensional. The solution is therefore not unique.
- (4) A 5×27 matrix can have 6 linearly independent columns.
Solution: F $\text{rk}(A) \leq \min(m, n) = 5$.
- (5) Suppose that A is an $n \times n$ matrix and $B \in \mathbb{R}^n$ a vector such that $Ax = B$ has infinitely many solutions. Then the columns of A are linearly dependent.
Solution: T If $Ax = B$ has infinitely many solutions, then $\text{null}(A) > 0$, and so $\text{rk}(A) < n$.
- (6) Suppose A is a 3×7 matrix such that $Ax = B$ is solvable for every $B \in \mathbb{R}^3$. Then A has 3 linearly independent rows.
Solution: T If $Ax = B$ is solvable for every B , then $\text{rk}(A) = 3$, so the rows are linearly independent.
- (7) Suppose that A is a matrix such that $\text{colsp}(A)$ and $\text{nullsp}(A)$ are both 2-dimensional. Then A must be a 4×4 matrix.
Solution: F The rank-nullity theorem yields that A must have 4 columns. However, if we start with a matrix A satisfying this property, and add a zero row, it will still satisfy the property.
- (8) Suppose that A is an $n \times n$ matrix such that $Ax = B$ is solvable for every $B \in \mathbb{R}^n$. Then for every $n \times n$ matrix C , there exists a matrix D such that $AD = C$.
Solution: T A is nonsingular, so let $D = A^{-1}C$.
- (9) The nullspace of a 3×4 matrix cannot consist only of the zero vector.
Solution: T $\text{rk}(A) \leq 3$, so $\text{null}(A) \geq 1$.
- (10) The nullspace of a 4×3 matrix cannot consist only of the zero vector.
Solution: F Any rank 3 4×3 matrix A will have this property.
- (11) Let $S = \{v_1, v_2, v_3, v_4, v_5\}$ be a set of vectors in \mathbb{R}^4 that spans \mathbb{R}^4 . Every subset of four vectors of S spans \mathbb{R}^4 .
Solution: F One of the v_i could be the zero vector.

- (12) The set of all vectors of the form $(1, x, y) \in \mathbb{R}^3$, where $x, y \in \mathbb{R}$, is a subspace of \mathbb{R}^3 .

Solution: F It does not contain 0.

- (13) Let u, v, w be elements of a vector space V , and let $a = u+v, b = w$. Then $\text{span}\{a, b\}$ is contained in, but not necessarily equal to $\text{span}\{u, v, w\}$.

Solution: T The span is obviously contained in that of $\{u, v, w\}$. If the latter are linearly indep, the spans will not be equal.

- (14) The set of all vectors of the form $(x, x^2) \in \mathbb{R}^2$, as x ranges over the real numbers, forms a subspace of \mathbb{R}^2 .

Solution: F $(1, 1) + (2, 4) = (3, 5)$ which is not in the subset.

- (15) All vector spaces are finite-dimensional.

Solution: F Consider the vector space of polynomials.