

CSE 313  
Final Examination  
May 7, 2004

Question 1: {20 pts}

Derive an expression for the scalar,  $\gamma$ , as a function of the vectors,  $u, v \in R^n$ , that will balance the following equation. (Make sure to show your work)

$$(I - uv^T)^{-1} = (I - \gamma(uv^T))$$

Use this result to invert the following matrix:

$$\begin{pmatrix} 2 & -1 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 2 & -2 & 1 & -2 \\ 1 & -1 & 0 & 0 \end{pmatrix}$$

Question 2: {15 pts}

Determine whether the solutions to the following differential equation are stable or unstable:  $\ddot{x} = -5\dot{x} - 4x$

Question 3: {15 pts}

If  $A$  is a square matrix prove that the absolute value of the determinant of  $A$ ,  $|\det(A)|$ , is equal to the product of its singular values.

Question 4: { 10 pts }

If  $y \in \text{Range}(A)$  and  $z \in \text{Null}(A^T)$  for some matrix,  $A \in R^{m \times n}$ , show that  $y^T z = 0$ .

Question 5: { 15 pts }

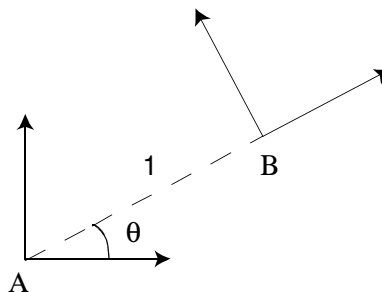
If  $\{v_1 \cdots v_n\}$  are orthonormal vectors,  $v_i \cdot v_j = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$ , and  $x = \sum_i \alpha_i v_i$  show that  $\|x\|^2 = \sum_i \alpha_i^2$ .

Based on this result, explain why dropping small Fourier coefficients is an effective strategy for compressing audio signals.

Question 6: { 15 pts }

Consider the figure shown below, let  $x_A, y_A$  denote the coordinates of a point with respect to frame A and  $x_B, y_B$  denote the coordinates of the same point with respect to frame B. These coordinate values can

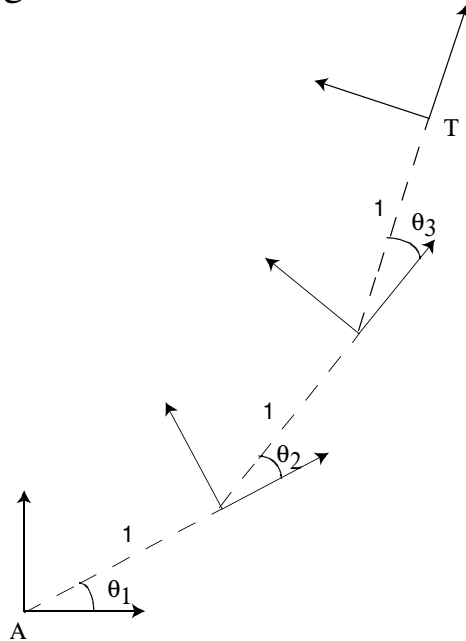
be related by the following equation. 
$$\begin{pmatrix} x_A \\ y_A \\ 1 \end{pmatrix} = g_{AB} \begin{pmatrix} x_B \\ y_B \\ 1 \end{pmatrix}$$



Give an expression for the 3 by 3 matrix  $g_{AB}$ .

Let  $g_{AT}$  denote the 3 by 3 matrix that relates coordinate frames A and T in the figure below. Using your previous result, express  $g_{AT}$  as

the product of a number of simpler coordinate transformations depending on the angles,  $\theta_1, \theta_2, \theta_3$ .



Question 7: { 15 pts }

If  $A$  is a skew-symmetric matrix,  $A^T = -A$ , show that  $x^T Ax = 0$  for all  $x \in R^n$

Question 8: { 15 pts }

If  $R \in R^{n \times n}$  is an orthonormal matrix,  $R^T \times R = I$ , show that:

1. All of the eigenvalues of  $R$  lie on the unit circle in the complex plane, that is  $\|\lambda\|^2 = \lambda \times \lambda^* = 1$ .
2. All eigenvectors of  $R$  are also eigenvectors of  $R^T$ .
3. If  $v_1, v_2 \in R^n$  are eigenvectors of  $R$  corresponding to distinct eigenvalues then they must be orthogonal,