

Name: \_\_\_\_\_ PennID: \_\_\_\_\_

**Math 240 Final Exam**  
**December 14, 2017**

Encircle your Professor, TA and recitation time below:

Professor	Simmons	Wibmer	Zhu	
Nibras Islam	We 8-9	We 9-10	Fr 8-9	Fr 9-10
Patrick Emedom-Nnamdi	We 8-9	We 9-10	Fr 8-9	Fr 9-10
Brian Luo	Mo 8-9	Mo 9-10	We 8-9	We 9-10
Benjamin Foster	Tu 8:30-9:30	Tu 9:30-10:30	Th 8:30-9:30	Th 9:30-10:30

**Instructions**

Turn off and put away your cell phone. Please write your Name and PennID on the top of this page and encircle your professor, TA and recitation time. Please sign and date the pledge below. No calculators or any other electronic devices are allowed during this exam. You may use a cheat sheet but no other material. Read each question carefully, and answer each question completely. Show all of your work. Write all your solutions clearly and legibly; no credit will be given for illegible solutions. Please try to be as organized as possible and clearly indicate your final solution (in the space provided). If any question is not clear, ask for clarification.

#	Points	Score
1	10	
2	10	
3	10	
4	10	
5	10	
6	10	
7	10	
8	10	
9	10	
10	10	
11	10	
12	10	
Total	120	

My signature below certifies that I have complied with the University of Pennsylvania's Code of Academic Integrity in completing this examination.

\_\_\_\_\_  
Signature

\_\_\_\_\_  
Date

**Problem 1 (10 pts):** Decide whether the following statements are true or false. You do NOT have to justify your answer. (Please indicate your answer by encircling “true” or “false”.)

1. The determinant of a matrix whose entries are all positive must be positive.

True                      False

2. If  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  is a basis for  $\mathbb{R}^n$  and  $A$  is an invertible  $n \times n$ -matrix, then  $\{A\mathbf{v}_1, \dots, A\mathbf{v}_n\}$  must also be a basis for  $\mathbb{R}^n$ .

True                      False

3. There is a unique linear transformation  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  that takes both  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  to  $\begin{bmatrix} -2 \\ 3 \end{bmatrix}$ .

True                      False

4. If  $L$  is a linear differential operator and  $y_1, y_2$  are solutions to  $Ly = F(x)$ , then  $y_1 - y_2$  is a solution to  $Ly = 0$ .

True                      False

5. If  $A^2$  is diagonalizable, then also  $A$  must be diagonalizable.

True                      False

**Problem 2 (10 pts):** True or False? You need to justify your answer to receive credit!

1. If  $A$  and  $B$  share a common eigenvector  $\mathbf{v}$ , then  $AB - BA$  is not invertible.

Circle one: True    False

Justification:

2. A polynomial differential operator of order 5, annihilates every polynomial of degree less than or equal to 4.

Circle one: True    False

Justification:

**Problem 3 (10 pts):** Compute the reduced row-echelon form, the rank and a basis for the nullspace for the following matrix  $A$ :

$$A = \begin{bmatrix} 0 & 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 4 & 6 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix}$$

RREF( $A$ ) = \_\_\_\_\_ rank( $A$ ) = \_\_\_\_ basis: \_\_\_\_\_

Problem 4 (10 pts): If  $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$  and  $\det(A) = 5$ , what is

$$\begin{vmatrix} 2a & d+3a & g \\ 2b & e+3b & h \\ 2c & f+3c & i \end{vmatrix}?$$

$\det(A) =$  \_\_\_\_\_

**Problem 5 (10 pts):** Let  $S$  be the subset of  $M_{2 \times 2}(\mathbb{R})$  consisting of all  $2 \times 2$ -matrices whose entries add up to zero. Show that  $S$  is a subspace of  $M_{2 \times 2}(\mathbb{R})$ .

**Problem 6 (10 pts):**

1. Let  $T : \mathbb{R}^3 \rightarrow P_3(\mathbb{R})$  be the linear transformation defined by

$$T \left( \begin{bmatrix} a \\ b \\ c \end{bmatrix} \right) = 2a - (a + b - c)x + (2c - a)x^3.$$

Compute  $[T]_B^C$  relative to the standard bases  $B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$  and  $C = \{1, x, x^2, x^3\}$ .

$[T]_B^C =$  \_\_\_\_\_

2. Compute  $[T(\mathbf{v})]_C$  for  $\mathbf{v} = \begin{bmatrix} 2 \\ -1 \\ 5 \end{bmatrix}$ .

$[T(\mathbf{v})]_C =$  \_\_\_\_\_

**Problem 7 (10 pts):** Decide whether or not the matrix  $A$  is diagonalizable. If so, find an invertible matrix  $S$  and a diagonal matrix  $D$  such that  $S^{-1}AS = D$ .

$$A = \begin{bmatrix} -4 & -3 & 3 \\ 6 & 5 & -3 \\ 0 & 0 & 2 \end{bmatrix}$$

(Hint:  $\lambda = 2$  is an eigenvalue of  $A$ .)

Diagonalizable? Yes    No

If yes,  $S =$  \_\_\_\_\_  $D =$  \_\_\_\_\_

**Problem 8 (10 pts):** Suppose  $A$  is a  $4 \times 4$  defective matrix with characteristic polynomial

$$p(\lambda) = (\lambda + 2)^2(\lambda - 1)(\lambda + 1).$$

1. Find the algebraic multiplicity and geometric multiplicity of  $-2$ . Briefly explain your reasoning.

algebraic multiplicity: \_\_\_\_\_ geometric multiplicity: \_\_\_\_\_

2. What is the rank of  $A + 2I$ ? Briefly explain your reasoning.

$\text{rank}(A + 2I) =$  \_\_\_\_\_

3. Find the rank of  $A$ . Briefly explain your reasoning.

$\text{rank}(A) =$  \_\_\_\_\_

**Problem 9 (10 pts):** Solve the following initial value problem:

$$y'' + y' - 6y = 10e^{2x}, \quad y(0) = 0, \quad y'(0) = 7.$$

$y(x) =$  \_\_\_\_\_

**Problem 10 (10 pts):** Determine the general solution of  $\mathbf{x}' = A\mathbf{x}$  for

$$A = \begin{bmatrix} 3 & 1 & 0 \\ -1 & 5 & 0 \\ 0 & 0 & 4 \end{bmatrix}.$$

(**Hint:**  $\det(A - \lambda I) = -(\lambda - 4)^3$ .)

$\mathbf{x}(t) =$  \_\_\_\_\_

**Problem 11 (10 pts):** Find the general solution to the following linear differential equation, given that  $x^2$  is a solution.

$$x^2y'' - 4xy' + 6y = 0, \quad x > 0.$$

$y(t) =$  \_\_\_\_\_

**Problem 12 (10 pts):** Characterize the equilibrium point of

$$\mathbf{x}'(t) = \begin{bmatrix} 1 & 5 \\ -2 & 3 \end{bmatrix} \mathbf{x}(t)$$

as:

- stable, unstable, neither stable or unstable and
- node, saddle point, proper node, degenerate node, center, spiral point.

You need to justify your answer.

circle one: stable    unstable    neither

circle one: node    saddle point    proper node    degenerate node    center    spiral point

Scratch paper

Scratch paper