

## Homework 9 Solutions

- 2 From discussion in recitation,  $\mathcal{L}((R^2)^2, R)$  is the dual of  $R^2 \otimes_R R^2$ . So it suffices to show that  $R^2 \otimes_R R^2$  has dimension 4. By definition, it has a basis  $e_1 \otimes e_1, e_1 \otimes e_2, e_2 \otimes e_1, e_2 \otimes e_2$ , and so  $\mathcal{L}((R^2)^2, R)$  has dimension four. The other two cases are trickier. Let  $\phi \in \mathcal{L}^s((R^2)^2, R)$ . Then  $\phi(m, n) = \phi(n, m)$ . So,  $\tilde{\phi}(\sum a_{ij} e_i \otimes e_j)$  must have  $a_{ij} = a_{ji}$ , and any map with this condition is symmetric. Thus,  $\phi(ae_1 + be_2, ce_1 + de_2) = ac\phi(e_1, e_1) + (ad + bc)\phi(e_1, e_2) + bd\phi(e_2, e_2)$ . Thus, the space of symmetric maps is dual to the submodule of  $R^2 \otimes_R R^2$  generated by  $e_1 \otimes e_1, e_1 \otimes e_2, e_2 \otimes e_2$ , and thus has dimension three. So now, we must determine what submodule of  $R^2 \otimes_R R^2$  the space  $\mathcal{L}^{alt}((R^2)^2, R)$  is dual to. For an alternating map  $\phi$ , we have  $\phi(ae_1 + be_1, ce_1 + de_2) = ac\phi(e_1, e_1) + ad\phi(e_1, e_2) + bc(\phi(e_2, e_1) + db\phi(e_2, e_2))$ , but also that  $\phi(e_1, e_1) = \phi(e_2, e_2) = 0$  and  $\phi(e_1, e_2) = -\phi(e_2, e_1)$ . Thus,  $\phi(ae_1 + be_2, ce_1 + de_2) = (ad - bc)\phi(e_1, e_2)$ , and so  $\mathcal{L}^{alt}((R^2)^2, R)$  is dual to the span on  $e_1 \otimes e_2$ , and so is one dimensional, as desired.
- 3 We must show that this set is linearly independent and spanning. First, spanning. Let  $f : T \rightarrow R$  any function. Set  $a_i = f(x_i)$ , for some ordering of  $T = \{x_1, \dots, x_n\}$ . Then look at  $\sum a_i f_{x_i}$ . We claim that this is  $f$ . Applying it to  $x_j$ , we obtain  $\sum a_i f_{x_i}(x_j) = \sum a_i \delta_{ij} = a_j = f(x_j)$ , and so  $f = \sum a_i f_{x_i}$ . Now, linear independence. Let  $f = \sum a_i f_{x_i} = 0$ . Then,  $f(x_j) = 0$ , and so  $\sum a_i f_{x_i}(x_j) = \sum a_i \delta_{ij} = a_j = 0$ , but this must hold for all  $j$ , and so all the coefficients must be 0. Thus, we have a spanning set.
- 3 Let  $A$  be an integer matrix whose inverse,  $A^{-1}$ , is also an integer matrix. Then  $AA^{-1} = I$ . Taking determinants, we have  $\det(AA^{-1}) = \det I = 1$ . But  $\det AA^{-1} = \det A \det A^{-1}$ , and so  $\det A \det A^{-1} = 1$ . Thus,  $\det A$  is a unit in  $\mathbb{Z}$ , and so must be  $\pm 1$ .

6 [a]

Let  $A, B, C$  as in the problem. Then we note that for any matrix, there's a larger field such that it is equivalent to an upper triangular matrix, and that determinant isn't changed by changing between equivalent matrices. Let  $A', B'$  be upper triangular matrices equivalent to  $A, B$ . Then, the whole matrix  $\begin{pmatrix} A' & C \\ 0 & B' \end{pmatrix}$  is upper triangular, and has determinant  $\det A' \det B' = \det A \det B$ . To see that this

is the determinant of  $\begin{pmatrix} A & C \\ 0 & B \end{pmatrix}$ , we note that we can get from this matrix to the one we want by using a change of basis block matrix.

(a) For this, the same trick suffices, and you can turn each  $A_i$  into an upper triangular matrix without affecting any determinants.

17 By Cramer's Rule,  $x_i = \Delta_i/\Delta$ , so we will merely compute  $\Delta_i$  and  $\Delta$  and declare solutions.

a

$$\Delta = \det \begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 4 \\ -1 & -1 & -1 \end{pmatrix} = 2$$

$$\Delta_1 = \det \begin{pmatrix} 1 & 1 & 1 \\ 1 & 3 & 4 \\ 0 & -1 & -1 \end{pmatrix} = 1,$$

$$\Delta_2 = \det \begin{pmatrix} 1 & 1 & 1 \\ 2 & 1 & 4 \\ 1 & 0 & -1 \end{pmatrix} = 4,$$

$$\Delta_3 = \det \begin{pmatrix} 1 & 1 & 1 \\ 2 & 3 & 1 \\ -1 & -1 & 0 \end{pmatrix} = -3$$

and so  $x = 1/2, y = 2, z = -3/2$ .

b Similarly, here,

$$\Delta = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \\ 1 & 1 & 4 & 5 \\ 1 & 1 & 5 & 6 \end{pmatrix} = -1,$$

$$\Delta_1 = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 4 \\ 1 & 1 & 4 & 5 \\ 0 & 1 & 5 & 6 \end{pmatrix} = -4,$$

$$\Delta_2 = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & 3 & 4 \\ 1 & 1 & 4 & 5 \\ 1 & 0 & 5 & 6 \end{pmatrix} = 2,$$

$$\Delta_3 = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 0 & 4 \\ 1 & 1 & 1 & 5 \\ 1 & 1 & 0 & 6 \end{pmatrix} = 4,$$

$$\Delta_4 = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 0 \\ 1 & 1 & 4 & 1 \\ 1 & 1 & 5 & 0 \end{pmatrix} = -3,$$

so  $x = 4, y = -2, z = -4, w = -3$